

**Draft Recommendation for
Space Data System Standards**

**RE-ENTRY DATA
MESSAGE**

DRAFT RECOMMENDED STANDARD

CCSDS 508.1-R-1

RED BOOK

June 2018

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FOREWORD

This document is a draft CCSDS Recommended Standard for a Re-entry Data Messages (RDM) and has been prepared by the CCSDS. The RDM described in this document is intended for re-entry (prediction) information exchange between interested parties.

Through the process of normal evolution, it is expected that expansion, deletion, or modification of this document may occur. This Recommended Standard is therefore subject to CCSDS document management and change control procedures, which are defined in the *Organization and Processes for the Consultative Committee for Space Data Systems* (CCSDS A02.1-Y-4). Current versions of CCSDS documents are maintained at the CCSDS Web site:

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PREFACE

This document is a draft CCSDS Recommended Standard. Its 'Red Book' status indicates that the CCSDS believes the document to be technically mature and has released it for formal review by appropriate technical organizations. As such, its technical contents are not stable, and several iterations of it may occur in response to comments received during the review process.

Implementers are cautioned **not** to fabricate any final equipment in accordance with this document's technical content.

Recipients of this draft are invited to submit, with their comments, notification of any relevant patent rights of which they are aware and to provide supporting documentation.

DOCUMENT CONTROL

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1 INTRODUCTION

1.1 PURPOSE AND SCOPE

The Re-entry Data Message (RDM) Recommended Standard (henceforth ‘the RDM’ or ‘this standard’) specifies a standard message format to be used in the exchange of spacecraft re-entry information between Space Situational Awareness (SSA) or Space Surveillance and Tracking (SST)¹ data providers, satellite owners/operators, and other parties. These messages can be used to inform spacecraft owners/operators of predicted re-entries or warn civil protection agencies about potential ground impacts.

The RDM will:

- a) facilitate interoperability and enable consistent warning between data providers who supply re-entry prediction data and the entities who use it;
- b) facilitate the automation of re-entry prediction processes; and
- c) provide critical information to enable timely re-entry decisions (e.g., a change in the controlled re-entry strategy).

The document also includes informative descriptions of re-entry prediction methods and data.

1.2 APPLICABILITY

The RDM is applicable to Space Surveillance and Tracking activities, spacecraft operations, and other ‘ground’ based activities (e.g., civil protection, civil and military aviation) where re-entering space objects are concerns. It contains the specifications for an RDM designed for re-entry prediction (though it can be used post-facto as well) information exchange between originators of re-entry data and recipients. Re-entry data includes remaining orbital lifetime, start and end of the re-entry and impact windows, impact location, and object physical properties. Further information about the types of data exchanged can be found in section 3.

The RDM is suitable for both manual and automated interaction, and for machine-to-machine interfaces because of the large amount of data present. The RDM is self-contained, but it can be paired with other Navigation Data Messages to enhance its functionality. For example, an RDM could be paired with several Orbit Parameter Messages (OPM—reference [1], section 3) to exchange state vectors at critical epochs (last orbit determination, current, re-entry, etc.) or with one Orbit Ephemeris Message (OEM—reference [1], section 5) to give the trajectory for (most of) the re-entry. The presence of user defined keywords allows other information to be exchanged after being specified in an Interface Control Document (ICD); ICDs are not necessary for most RDM exchanges, but are expected in some cases (especially if ODMs are

¹ The term SSA is more commonly used in the US, while SST is preferred in Europe. This document uses SST hereafter.

to be exchanged for object position). The CCSDS Navigation Working Group should be informed of new optional keywords for possible inclusion in future revisions of the standard.

It is desirable that RDM originators maintain consistency with respect to the optional keywords provided in their implementations; i.e., it is desirable that the composition of the RDMs provided not change on a frequent basis.

This standard is applicable only to the message format and content, not to its transmission or to the algorithms used to produce the data within. The method of transmitting the message between exchange partners is beyond the scope of this document and could be specified in an ICD. The methods used to predict re-entries and calculate the associated data (e.g., probability of ground impact and impact location) are also outside the scope of this standard.

1.3 DOCUMENT STRUCTURE

Section 2 provides a short overview of the CCSDS RDM.

Section 3 describes the structure and content of the ‘keyword = value’ (KVN) version of the RDM.

Section 4 describes the structure and content of the XML version of the RDM.

Section 5 describes the data and syntax of RDM messages, both the KVN and XML versions.

Annex A shows the Implementation Conformance Statement (ICS), listing all the requirements an RDM implementation should meet.

Annex B lists agreed values for some of the keywords in this standard.

Annex C discusses security, SANA and patent issues.

Annex D provides RDM examples.

Annex E lists the abbreviations and acronyms used in this document.

Annex F lists the requirements this standard was designed to meet.

Annex G presents a summary sheet that shows which optional metadata entries should be present for the data blocks in the message.

Annex H describes the types of information exchanged in an RDM.

Annex I provides a list of informative references.

1.4 NOMENCLATURE

1.4.1 NORMATIVE TEXT

The following conventions apply for the normative specifications in this Recommended Standard:

- a) the words ‘shall’ and ‘must’ imply a binding and verifiable specification;
- b) the word ‘should’ implies an optional, but desirable, specification;
- c) the word ‘may’ implies an optional specification;
- d) the words ‘is’, ‘are’, and ‘will’ imply statements of fact.

NOTE – These conventions do not imply constraints on diction in text that is clearly informative in nature.

1.4.2 INFORMATIVE TEXT

In the normative sections of this document, informative text is set off from the normative specifications either in notes or under one of the following subsection headings:

- Overview;
- Background;
- Rationale;
- Discussion.

1.5 CONVENTIONS AND DEFINITIONS

The following conventions for unit notations apply throughout this standard. The the extent possible, an effort has been made to use units that are part of the International System of Units (SI—defined in reference [2]); units are either SI base units, SI derived units, or units outside the SI that are accepted for use with the SI. The units used within this document are as follows:

- km: kilometers;
- m: meters;
- d: days (86400 s);
- s: seconds of time;
- kg: kilograms;
- %: percent.

For compound units the following conventions are used:

- multiplication is denoted with a single asterisk, '*' (e.g., 'kg*s');
- division is denoted with a single forward slash, '/' (e.g., 'km/s');
- exponents are denoted with a double asterisk, '**' (e.g., 'km**2').

The usual mathematical conventions for operation order (e.g., exponents before multiplication) apply.

The following conventions apply when referring to Earth re-entry prediction simulations:

- a) *short-term re-entry prediction* refers to all simulations where the object's altitude is below 200 km, typically covering the last few days (up to a few weeks) before re-entry;
- b) *long and medium term prediction* refers to all simulations where the object's altitude is above 200 km, typically spanning from a few weeks to years before re-entry.

The term 'ASCII' is generally used in this document to refer to the text character set defined in reference [3]. The term 'n/a' is used to mean 'not applicable' or 'not available'.

1.6 REFERENCES

The following publications contain provisions which, through reference in this text, constitute provisions of this document. At the time of publication, the editions indicated were valid. All publications are subject to revision, and users of this standard are encouraged to investigate the possibility of applying the most recent editions of the publications indicated below. The CCSDS Secretariat maintains a register of currently valid CCSDS publications.

- [1] *Orbit Data Messages*. Issue 2. Recommendation for Space Data System Standards (Blue Book), CCSDS 502.0-B-2. Washington, D.C.: CCSDS, November 2009.
- [2] *The International System of Units (SI)*. 8th ed., 2006; updated in 2014. Sèvres, France: BIPM, 2006.
- [3] *Information Technology—8-Bit Single-Byte Coded Graphic Character Sets—Part 1: Latin Alphabet No. 1*. International Standard, ISO/IEC 8859-1:1998. Geneva: ISO, 1998.
- [4] Henry S. Thompson, et al., eds. *XML Schema Part 1: Structures*. 2nd ed. W3C Recommendation. N.p.: W3C, October 2004.
- [5] Paul V. Biron and Ashok Malhotra, eds. *XML Schema Part 2: Datatypes*. 2nd ed. W3C Recommendation. N.p.: W3C, October 2004.

- [6] “Organizations.” Space Assigned Numbers Authority (SANA). <http://sanaregistry.org/r/organizations/>.
- [7] “United Nations Register of Objects Launched into Outer Space.” UNOOSA. <http://www.unoosa.org/oosa/en/spaceobjectregister/>.
- [8] “Conjunction Data Message CATALOG_NAME.” Space Assigned Numbers Authority (SANA). https://sanaregistry.org/r/cdm_catalog.
- [9] *XML Specification for Navigation Data Messages*. Issue 1. Recommendation for Space Data System Standards (Blue Book), CCSDS 505.0-B-1. Washington, D.C.: CCSDS, December 2010.
- [10] *Time Code Formats*. Issue 4. Recommendation for Space Data System Standards (Blue Book), CCSDS 301.0-B-4. Washington, D.C.: CCSDS, November 2010.

2 OVERVIEW

2.1 OVERVIEW

This section provides a high-level overview of the Re-entry Data Message, a message format designed to help the exchange of re-entry data between originators of re-entry data, spacecraft operators, and other interested entities. The originators of re-entry data can be SST entities or even the spacecraft operators themselves (e.g., for a controlled re-entry).

2.2 RDM CONTENT

The RDM is an ASCII format, encoded either as plain text (usually referred to as KVN) or XML (references [3], [4], and [5]). This standard describes both.

The RDM contains information about a single re-entry event:

- information about the message itself (creation date, originator, etc.);
- identification of the re-entering object (name, ID);
- basic re-entry information (mandatory): remaining orbital lifetime, whether the re-entry is controlled or not, and which celestial body the object is orbiting;
- more complex re-entry information (optional): re-entry and impact windows, impact location and probabilities, state vector, object properties, the orbit determination (OD) process, and observations used to predict the re-entry.

The information is used by satellite operators, civil protection, or aviation authorities to assess the re-entry risk and plan any needed mitigation measures.

The RDM is not limited to man-made objects re-entering the Earth's atmosphere. It could be used for any entry/impact event by specifying the appropriate CENTER_NAME, REF_FRAME, and OBJECT_TYPE values (e.g., a space probe landing on Venus).

3 RE-ENTRY DATA MESSAGE STRUCTURE AND CONTENT (KVN)

3.1 OVERVIEW

This section contains a description of the structure, content, and keywords allowed in a Re-entry Data Message.

3.2 GENERAL

3.2.1 The RDM shall be plain text consisting of re-entry (prediction) data for a single re-entry event.

3.2.2 The RDM in Keyword Value Notation (KVN) shall consist of digital data represented as ASCII text lines. The RDM shall contain the following:

- a) a header;
- b) a metadata section;
- c) a data section.

NOTES

- 1 KVN messages contain one keyword per line (specified in 5.3.2.4).
- 2 The standard order of keywords in the KVN representation is fixed by this standard, as listed in tables 3-1, 3-2, and 3-3 (specified in 5.3.2.10).

3.2.3 The RDM file naming scheme should be agreed to on a case-by-case basis between the participating agencies, typically specified in an ICD. In general, the file name syntax and length must not violate computer constraints for those computing environments in use by Member Agencies for processing re-entry data.

3.2.4 The exchange method for RDMs should be determined on a case-by-case basis and should be documented in an ICD.

3.3 RDM HEADER

The RDM header shall only consist of the KVN elements defined in table 3-1, which specifies for each header item:

- a) the keyword to be used;
- b) a short description of the item;
- c) examples of allowed values;
- d) whether the item is mandatory (M) or optional (O).

Table 3-1: RDM KVN Header

Keyword	Description of values	Examples of values	M/O
CCSDS_RDM_VERS	Format version in the form of 'x.y', where 'y' is incremented for corrections and minor changes, and 'x' is incremented for major changes.	1.0	M
COMMENT	Comments (allowed in the RDM Header only immediately after the RDM version number).	COMMENT This is a comment	O
CREATION_DATE	File creation date and time in UTC. The format is defined in 5.3.3.5.	2001-11-06T11:17:33 2002-204T15:56:23	M
ORIGINATOR	Creating agency or operator (value should be taken from the abbreviation column in the SANA organizations registry, reference [6]). The country of origin should also be provided where the originator is not a national space agency.	DLR ESA	M
MESSAGE_ID	ID that uniquely identifies a message from a given originator. The format and content of the message identifier value are at the discretion of the originator.	201113719185	M

3.4 RDM METADATA

3.4.1 The RDM metadata shall only consist of the KVN elements defined in table 3-2, which specifies for each metadata item:

- a) the keyword;
- b) a short description of the item;
- c) normative values or examples of values;
- d) whether the values are normative (N—all values allowed are in the list in the third column) or examples of values allowed (E);
- e) whether the item is mandatory (M) or optional (O).

3.4.2 Mandatory items shall appear in every RDM metadata section. Items that are not mandatory may or may not appear, at the discretion of the data producer, based on the requirements of the data and its intended application (an RDM Summary Sheet that illustrates the relationships between data types and metadata can be found in annex G).

Table 3-2: RDM KVN Metadata

Keyword	Description	Examples of values	N/E	M/O
COMMENT	Comments (allowed only at the beginning of RDM metadata).	COMMENT This is a comment	E	O
General information identifying the object, which celestial body it is orbiting and the time system of all the epoch information				
OBJECT_NAME	Object name for which the orbit state is provided. There is no CCSDS-based restriction on the value for this keyword, but it is recommended to use names from the UN OOSA registry—reference [7], which includes Object name and international designator of the participant (formatting rules specified in 5.2.3.3). For objects that are not in the UN OOSA registry, either a descriptive name (e.g., DEBRIS, if the object is identified as space debris) or UNKNOWN should be used.	SENTINEL-1A GOCE ENVISAT BRIZ R/B DEBRIS UNKNOWN	E	M
INTERNATIONAL_DESIGNATOR	The full international designator (COSPAR ID) for the object. Values shall have the format YYYY-NNNP{PP}, where: YYYY = year of launch; NNN = three-digit serial number of launch (with leading zeros); P{PP} = at least one capital letter for the identification of the part brought into space by the launch. In cases where the object has no international designator, the value UNKNOWN should be used (formatting rules specified in 5.2.3.3).	2010-012C 2016-001A 1985-067CD UNKNOWN	E	M
CATALOG_NAME	The satellite catalog used for the object (formatting rules specified in 5.2.3.3). The name should be taken from the appropriate SANA registry for catalog names, reference [8].	SATCAT ESA SST	E	O
OBJECT_DESIGNATOR	The CATALOG_NAME satellite catalog designator for the object (formatting rules specified in 5.2.3.3).	37451 125387U	E	O
OBJECT_TYPE	The object type.	PAYLOAD ROCKET BODY DEBRIS OTHER UNKNOWN	N	O
OBJECT_OWNER	Owner of the object (e.g., company, agency, or country owning the satellite). The value should be taken from the abbreviation column in the SANA organizations registry, reference [6].	DLR INTELSAT ESA UNKNOWN	E	O

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Keyword	Description	Examples of values	N/E	M/O
OBJECT_OPERATOR	Operator of the object (e.g., company, agency, or country operating the satellite). The value should be taken from the abbreviation column in the SANA organizations registry, reference [6].	ESA EUMETSAT	E	O
CONTROLLED_REENTRY	Specification of whether the re-entry is controlled or not.	YES NO UNKNOWN	N	M
CENTER_NAME	Celestial body orbited by the object and origin of reference frame, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter.	EARTH MOON JUPITER	E	M
TIME_SYSTEM	Time system for all data/metadata. Use of values other than those in annex B, subsection B1 must be documented in an ICD.	UTC TAI	E	M
EPOCH_TZERO	Epoch from which the ORBIT_LIFETIME is calculated (formatting rules specified in 5.3.3.5).	2001-11-06T11:17:33 2002-204T15:56:23	E	M
The reference frame of the orbit data or the identifier of external ODM files				
REF_FRAME	Reference frame in which the (optional) orbit information will be provided. Use of values other than those in annex B, subsection B2 must be documented in an ICD. The reference frame must be the same for all data elements, with the exception of the covariance matrix, for which a different reference frame may be specified, and the ground impact data. This keyword becomes mandatory if state vectors are provided in the data section.	ITRF-97 EME2000 ICRF	E	O
REF_FRAME_EPOCH	Epoch of reference frame, if not intrinsic to the definition of the reference frame (formatting rules specified in 5.3.3.5).	2001-11-06T11:17:33 2002-204T15:56:23 Z	E	O
EPHEMERIS_NAME	Unique identifier of an external ephemeris file used or NONE.	NONE EPHEMERIS INTELSAT2	E	O

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Keyword	Description	Examples of values	N/E	M/O
The modeling used to determine the re-entry data				
GRAVITY_MODEL	The gravity model used in the simulation. The degree (D) and order (O) of the spherical harmonic coefficients applied should be given along with the name of the model.	EGM-96: 36D 36O JGM-2: 41D 41O	E	O
ATMOSPHERIC_MODEL	The atmosphere model(s) used in the simulation. If more than one model is used they should be listed on the same line and separated by a comma.	MSIS, JACCHIA 70 MSISE-90 NRLMSISE-00	E	O
SOLAR_FLUX_PREDICTION	The method used to predict the solar flux and geomagnetic indices.	MONTE CARLO PREDICTED: MLLRT	E	O
N_BODY_PERTURBATIONS	List of other bodies used in the simulation.	MOON, SUN JUPITER NONE	E	O
SOLAR_RAD_PRESSURE	Model used for the solar radiation pressure: either model name, or NO if solar radiation pressure was not modelled.	GSPM04 NO	E	O
EARTH_TIDES	Model used for solid Earth and ocean tides: either model name, or NO if tides were not modelled.	ESR NO	E	O
INTRACK_THRUST	Indicator on whether in-track thrust modeling was used in the simulation.	YES NO	N	O
REENTRY_ DISINTEGRATION	The aspects of disintegration during re-entry considered during simulations: none (the object was treated as a point mass), mass loss, break-ups, or both. It is a coarse indication on whether the impact area in the data covers potential fragments as well.	NONE MASS-LOSS BREAK-UP MASS-LOSS + BREAK-UP	N	O
IMPACT_UNCERTAINTY_METHOD	The method used to determine the impact location confidence interval(s).	NONE ANALYTICAL MONTE CARLO EMPIRICAL	N	O
Information about the previous and next messages to be issued				
PREVIOUS_MESSAGE_ID	ID of the previous RDM issued for this object.	ESA/2015- 563892348	E	O
PREVIOUS_MESSAGE_EPOCH	UTC Epoch of the previous RDM issued for this object (formatting rules specified in 5.3.3.5).	2001-11- 06T11:17:33	E	O
NEXT_MESSAGE_EPOCH	Scheduled UTC epoch of the next RDM for the same object (formatting rules specified in 5.3.3.5); N/A if no other message is scheduled.	2001-11- 06T11:17:33 N/A	E	O

3.5 RDM DATA

3.5.1 The RDM data section shall be formatted as logical blocks:

- atmospheric re-entry and ground impact data;
- state vector (including epoch);
- position/velocity covariance matrix (associated with the state vector and at the same epoch);
- object physical parameters;
- orbit determination parameters;
- user defined parameters.

3.5.2 The logical blocks of the RDM data section shall consist of KVN lines defined in table 3-3, which specifies:

- a) the keyword to be used;
- b) a description of the content;
- c) the units to be used;
- d) whether the item is mandatory (M) or optional (O).

Table 3-3: RDM KVN Data

Keyword	Description of values	Units	M/O
Atmospheric re-entry data			
COMMENT	Comments (allowed only at the beginning of each RDM data logical block).	n/a	O
ORBIT_LIFETIME	Time until re-entry: from the EPOCH_TZERO epoch in the metadata (days –double precision values allowed; integer values assumed to have .0 fractional part) to permanently crossing the altitude specified in REENTRY_ALTITUDE. If the NOMINAL_REENTRY_EPOCH keyword is present, the ORBIT_LIFETIME and NOMINAL_REENTRY_EPOCH should resolve to the same value.	d	M
LIFETIME_DISPERSION	Dispersion (1-sigma) of remaining orbit lifetime. LIFETIME_DISPERSION is a coarse value for long-term predictions, REENTRY_WINDOW_START and _END should be used for accurate results.	%	O

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

Keyword	Description of values	Units	M/O
REENTRY_ALTITUDE	Defined re-entry altitude over a spherical central body—once an object's altitude permanently drops below this value, it is considered to be captured by the central body's atmosphere.	km	M
NOMINAL_REENTRY_EPOCH	Predicted epoch at which the object's altitude permanently drops below NOMINAL_REENTRY_ALTITUDE (formatting rules specified in 5.3.3.5).	n/a	O
REENTRY_WINDOW_START	Start epoch of the predicted atmospheric re-entry window (formatting rules specified in 5.3.3.5).	n/a	O
REENTRY_WINDOW_END	End epoch of the predicted atmospheric re-entry window (formatting rules specified in 5.3.3.5).	n/a	O
Ground impact and burn-up data			
COMMENT	Comments (allowed only at the beginning of each RDM data logical block).	n/a	O
PROBABILITY_OF_IMPACT	Probability of any fragment's impacting the Earth (either land or sea; 0 to 1).	n/a	O
PROBABILITY_OF_BURN_UP	Probability of the entire object and any fragments' burning up during atmospheric re-entry (0 to 1).	n/a	O
PROBABILITY_OF_BREAK_UP	Probability of the object's breaking up during re-entry (0 to 1).	n/a	O
PROBABILITY_OF_LAND_IMPACT	Probability of any fragment's impacting solid ground (0 to 1).	n/a	O
PROBABILITY_OF_CASUALTY	Probability of the re-entry event's causing any casualties (severe injuries or deaths—0 to 1).	n/a	O
NOMINAL_IMPACT_EPOCH	Epoch of the predicted impact (formatting rules specified in 5.3.3.5).	n/a	O
IMPACT_WINDOW_START	Start epoch of the predicted impact window (formatting rules specified in 5.3.3.5).	n/a	O
IMPACT_WINDOW_END	End epoch of the predicted impact window (formatting rules specified in 5.3.3.5).	n/a	O
IMPACT_REF_FRAME	Reference frame of the impact location data. The value should be selected from those listed in annex B, subsection B4. Mandatory if NOMINAL_IMPACT_LON and NOMINAL_IMPACT_LAT are present.	n/a	O
NOMINAL_IMPACT_LON	Longitude of the predicted impact location with respect to the value of IMPACT_REF_FRAME.	deg	O
NOMINAL_IMPACT_LAT	Latitude of the predicted impact location with respect to the value of IMPACT_REF_FRAME.	deg	O
NOMINAL_IMPACT_ALT	Altitude of the impact location with respect to the value of IMPACT_REF_FRAME.	m	O

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

Keyword	Description of values	Units	M/O
IMPACT_1_CONFIDENCE	First (lowest) confidence interval for the impact location.	%	O
IMPACT_1_START_LON	Longitude of the start of the first confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_1_START_LAT	Latitude of the start of the first confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_1_STOP_LON	Longitude of the end of the first confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_1_STOP_LAT	Latitude of the end of the first confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_1_CROSS_TRACK	Cross-track size of the first confidence interval.	km	O
IMPACT_2_CONFIDENCE	Second confidence interval for the impact location. The IMPACT_1_* block must be present if IMPACT_2_* is used.	%	O
IMPACT_2_START_LON	Longitude of the start of the second confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_2_START_LAT	Latitude of the start of the second confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_2_STOP_LON	Longitude of the end of the second confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_2_STOP_LAT	Latitude of the end of the second confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_2_CROSS_TRACK	Cross-track size of the second confidence interval.	km	O
IMPACT_3_CONFIDENCE	Third (highest) confidence interval for the impact location. The IMPACT_2_* block must be present if IMPACT_3_* is used.	%	O
IMPACT_3_START_LON	Longitude of the start of the third confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_3_START_LAT	Latitude of the start of the third confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_3_STOP_LON	Longitude of the end of the third confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

Keyword	Description of values	Units	M/O
IMPACT_3_STOP_LAT	Latitude of the end of the third confidence interval along the ground track with respect to the value of IMPACT_REF_FRAME.	deg	O
IMPACT_3_CROSS_TRACK	Cross-track size of the third confidence interval.	km	O
State vector components in the coordinate system specified in the metadata (if any of the following elements are provided, then all of them must be present)			
COMMENT	Comments (allowed only at the beginning of each RDM data logical block).	n/a	O
EPOCH	Epoch at which the state vector is given (formatting rules specified in 5.3.3.5).	n/a	O
X	x-component of the object state vector.	km	O
Y	y-component of the object state vector.	km	O
Z	z-component of the object state vector.	km	O
X_DOT	x'-component of the object state vector.	km/s	O
Y_DOT	y'-component of the object state vector.	km/s	O
Z_DOT	z'-component of the object state vector.	km/s	O
Position/velocity covariance matrix (6x6 lower triangular form; if any of the following elements are provided, then all of them must be present; only COV_REF_FRAME can be omitted if it is the same as the orbit reference frame)			
COMMENT	Comments (allowed only at the beginning of each RDM data logical block).	n/a	O
COV_REF_FRAME	Reference frame for the covariance information, omitted if it is the same as REF_FRAME. Use of values other than those in annex B, subsection B3 must be documented in an ICD.	n/a	O
CX_X	Covariance matrix [1,1].	km**2	O
CY_X	Covariance matrix [2,1].	km**2	O
CY_Y	Covariance matrix [2,2].	km**2	O
CZ_X	Covariance matrix [3,1].	km**2	O
CZ_Y	Covariance matrix [3,2].	km**2	O
CZ_Z	Covariance matrix [3,3].	km**2	O
CX_DOT_X	Covariance matrix [4,1].	km**2/s	O
CX_DOT_Y	Covariance matrix [4,2].	km**2/s	O
CX_DOT_Z	Covariance matrix [4,3].	km**2/s	O
CX_DOT_X_DOT	Covariance matrix [4,4].	km**2/s**2	O
CY_DOT_X	Covariance matrix [5,1].	km**2/s	O
CY_DOT_Y	Covariance matrix [5,2].	km**2/s	O
CY_DOT_Z	Covariance matrix [5,3].	km**2/s	O
CY_DOT_X_DOT	Covariance matrix [5,4].	km**2/s**2	O
CY_DOT_Y_DOT	Covariance matrix [5,5].	km**2/s**2	O

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

Keyword	Description of values	Units	M/O
CZ_DOT_X	Covariance matrix [6,1].	km**2/s	O
CZ_DOT_Y	Covariance matrix [6,2].	km**2/s	O
CZ_DOT_Z	Covariance matrix [6,3].	km**2/s	O
CZ_DOT_X_DOT	Covariance matrix [6,4].	km**2/s**2	O
CZ_DOT_Y_DOT	Covariance matrix [6,5].	km**2/s**2	O
CZ_DOT_Z_DOT	Covariance matrix [6,6].	km**2/s**2	O
Object physical parameters			
COMMENT	Comments (allowed only at the beginning of each RDM data logical block).	n/a	O
MASS	Object mass.	kg	O
SOLAR_RAD_AREA	Object area exposed to Solar Radiation Pressure (SRP).	m**2	O
SOLAR_RAD_COEFF	Object radiation coefficient.	n/a	O
DRAG_AREA	Object cross-sectional area.	m**2	O
DRAG_COEFF	Object drag coefficient.	n/a	O
RCS	Object radar cross section.	m**2	O
BALLISTIC_COEFF	Object ballistic coefficient.	kg/m**2	O
THRUST_ACCELERATION	The object's acceleration due to in-track thrust used to propagate the state vector and covariance to NOMINAL_REENTRY_EPOCH (if a controlled re-entry).	m/s**2	O
Orbit determination (OD) parameters			
COMMENT	Comments (allowed only at the beginning of each RDM data logical block).	n/a	O
TIME_LASTOB_START	The start of a time interval (in the time system specified in the metadata) that contains the time of the last accepted observation. For an exact time, the time interval is of zero duration (i.e., same value as that of TIME_LASTOB_END). Formatting rules are specified in 5.3.3.5.	n/a	O
TIME_LASTOB_END	The end of a time interval (in the time system specified in the metadata) that contains the time of the last accepted observation. For an exact time, the time interval is of zero duration (i.e., same value as that of TIME_LASTOB_START). Formatting rules are specified in 5.3.3.5.	n/a	O
RECOMMENDED_OD_SPAN	The recommended OD time span calculated for the object (double precision).	d	O
ACTUAL_OD_SPAN	Based on the observations available and the RECOMMENDED_OD_SPAN, the actual time span used for the OD of the object (double precision).	d	O

Keyword	Description of values	Units	M/O
OBS_AVAILABLE	Number of observations available for orbit determination of the object.	n/a	O
OBS_USED	Number of observations accepted by the OD system.	n/a	O
TRACKS_AVAILABLE	Number of sensor tracks available for OD of the object.	n/a	O
TRACKS_USED	Number of sensor tracks accepted by the OD system.	n/a	O
RESIDUALS_ACCEPTED	The percentage of residuals accepted in the OD of the object.	%	O
WEIGHTED_RMS	The weighted root mean square of the residuals from batch OD.	n/a	O
User defined parameters (all such parameters must be described in an ICD)			
COMMENT	Comments (allowed only at the beginning of each RDM data logical block).	n/a	O
USER_DEFINED_x	User defined parameter, where x is replaced by a variable length user specified character string. Any number of user defined parameters may be included, if necessary to provide essential information that cannot be conveyed in COMMENT statements.	n/a	O

3.5.3 Table 3-3 contains seven logical blocks, each of which has a descriptive heading. These descriptive headings shall not be included in an RDM, unless they appear in a properly formatted COMMENT statement (KVN comments specified in 5.3.5, XML in 5.4.4).

3.5.4 COMMENT lines may be used at the beginning of each logical block of the data section (comment placing is further specified in 5.2.5.2).

3.5.5 The ORBIT_LIFETIME keyword is mandatory and shall be used to convey:

- a) whether it is short term or medium and long term re-entry prediction (defined in 1.5);
- b) for long and medium term predictions only, the remaining orbital lifetime.

3.5.6 For short term re-entry predictions the NOMINAL_REENTRY_EPOCH, REENTRY_WINDOW_START, and RE_ENTRY_WINDOW_END should be used.

3.5.7 If the NOMINAL_REENTRY_EPOCH, REENTRY_WINDOW_START, and RE_ENTRY_WINDOW_END keyword are present, their values should be used in computations, rather than those of the ORBIT_LIFETIME and LIFETIME_DISPERSION keywords.

3.5.8 If the NOMINAL_REENTRY_EPOCH keyword is present, the ORBIT_LIFETIME and NOMINAL_REENTRY_EPOCH keyword should resolve to the same value.

3.5.9 If a ground impact location is given, the `IMPACT_REF_FRAME` keyword shall be mandatory and at least `NOMINAL_IMPACT_LAT` and `NOMINAL_IMPACT_LON` shall be present. `NOMINAL_IMPACT_ALT` may be given as well.

3.5.10 If one confidence 'n' interval is present then all the values associated with interval 'n' shall be present: `IMPACT_n_CONFIDENCE`, `IMPACT_n_START_LON`, `IMPACT_n_START_LAT`, `IMPACT_n_STOP_LON`, `IMPACT_n_STOP_LAT`, and `IMPACT_n_CROSS_TRACK`.

3.5.11 If only one confidence interval is present then the `IMPACT_1_*` keywords shall be used.

3.5.12 If two confidence intervals are present then the `IMPACT_1_*` and `IMPACT_2_*` keywords shall be used.

3.5.13 If more than one confidence interval is present, then `IMPACT_1_CONFIDENCE` shall be smaller than `IMPACT_2_CONFIDENCE`, which in turn shall be smaller than `IMPACT_3_CONFIDENCE`, if it is present.

3.5.14 If the `RE_ENTRY_DISINTEGRATION` keyword in the metadata indicates that break-up was simulated, then the ground impact location keywords shall refer to all potential fragments related to the event; i.e., the `NOMINAL_IMPACT_LAT` and `_LON` will correspond to the highest probability of any fragment's impacting there, the confidence intervals will apply to all fragments, etc.

3.5.15 The probability of ground impact should be within five percent at the following four points for each confidence interval given: the start and end of the confidence interval in the along-track direction, and the nominal impact location \pm the cross-track confidence interval.

3.5.16 The state vector and covariance data are at the epoch specified by the `EPOCH` keyword in the data section. There are no restrictions on which epoch this is supposed to be (orbit determination epoch, message creation epoch, re-entry epoch, etc.). If the covariance block is present then the state vector shall be present as well.

3.5.17 If the state vector block is present then all elements in the block shall be present, with the exception of the comment line. No partial state vectors shall be present in an RDM. State vector values shall be expressed in standard double precision as related in 5.2.3.2.

3.5.18 Values in the covariance matrix shall be expressed in the applicable reference frame (`COV_REF_FRAME` keyword if used, or `REF_FRAME` keyword if not), and shall be presented sequentially from upper left [1,1] to lower right [6,6], lower triangular form, row by row, left to right. If the covariance block is present in the message, all covariance matrix elements shall be present. Variance and covariance values shall be expressed in standard double precision as related in 5.2.3.2.

3.5.19 Since re-entry prediction services are still in their infancy and some RDM originators might need to provide information that is not foreseen by this standard, a section of User

Defined Parameters may be included at the end of the data section. In principle, User Defined Parameters provide flexibility, but also introduce complexity, non-standardization, potential ambiguity, and potential processing errors. Accordingly, if used, the keywords and their meanings must be described in an ICD. User Defined Parameters, if included in an RDM, should be used as sparingly as possible; their use is not encouraged.

4 RE-ENTRY DATA MESSAGE STRUCTURE & CONTENT (XML)

4.1 OVERVIEW—THE RDM/XML SCHEMA

This section applies only to the XML version.

The RDM/XML schema is available on the SANA Web site. SANA is the registrar for the protocol registries created under CCSDS.

The RDM XML schema explicitly defines the permitted data elements and values acceptable for the XML version of the RDM message. The location of the RDM/XML schema is:

<http://sanaregistry.org/r/ndmxml/ndmxml-1.0-rdm-1.0.xsd>

Where possible this schema uses simple types and complex types used by the constituent schemas that make up Navigation Data Messages (specified in reference [9]).

4.2 RDM/XML BASIC STRUCTURE

4.2.1 Each RDM shall consist of a <header> and a <body>.

4.2.2 The RDM <body> shall consist of a single <segment> construct.

4.2.3 The RDM <segment> shall consist of a <metadata>/<data> pair, as shown in figure 4-1.

```

<header>
</header>
<body>
  <segment>
    <metadata>
    </metadata>
    <data>
    </data>
  </segment>
</body>

```

Figure 4-1: RDM XML Basic Structure

4.3 RDM/XML TAGS

4.3.1 An RDM XML tag shall be all uppercase if it corresponds directly to a KVN keyword from the header, metadata, or data sections.

4.3.2 There is an exception where there is not a strict correspondence between keywords in the KVN and tags in the XML implementations, specifically, the ‘CCSDS_RDM_VERS’ keyword from the RDM header. The ‘CCSDS_RDM_VERS’ keyword and its value shall appear as XML attributes rather than as an XML element.

4.3.3 RDM XML tags related to the XML message structure (i.e., that do not correspond directly to a KVN keyword) shall be in ‘lowerCamelCase’ (e.g., <header>, <segment>, <metadata>).

4.4 CONSTRUCTING AN RDM/XML INSTANCE

4.4.1 OVERVIEW

This subsection provides more detailed instructions for the user on how to create an XML message based on the ASCII-text KVN-formatted message described in 3.3 through 3.5.

4.4.2 XML VERSION

4.4.2.1 The first line in the instantiation shall specify the XML version:

```
<?xml version="1.0" encoding="UTF-8" ?>
```

4.4.2.2 This line must appear on the first line of each instantiation, exactly as shown.

4.4.3 BEGINNING THE INSTANTIATION: ROOT DATA ELEMENT

4.4.3.1 An RDM instantiation shall be delimited with the <rdm></rdm> root element tags using the standard attributes documented in reference [9], subsection 4.3.

4.4.3.2 The XML Schema Instance namespace attribute must appear in the root element tag of all RDM/XML instantiations, exactly as shown:

```
xmlns:xsi = "http://www.w3.org/2001/XMLSchema-instance"
```

4.4.3.3 If it is desired to validate an instantiation against the CCSDS Web-based schema, the xsi:noNamespaceSchemaLocation attribute must be coded as a single string of non-blank characters, with no line breaks, exactly as shown:

```
xsi:noNamespaceSchemaLocation="http://SANRegistry.org/r/ndmxml/ndmxml-1.0-master.xsd"
```

NOTE – The length of the value associated with the xsi:noNamespaceSchemaLocation attribute can cause the string to wrap to a new line; however, the string itself contains no breaks.

4.4.3.4 The final attributes of the <rdm> tag shall be 'id' and 'version'.

4.4.3.5 The 'id' attribute shall be 'id="CCSDS_RDM_VERS"'. The 'version' attribute shall be 'version="1.0"'.

NOTE – The following example root element tag for an RDM instantiation combines all the directions in the preceding several subsections:

```
<?xml version="1.0" encoding="UTF-8"?>
<rdm xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xsi:noNamespaceSchemaLocation=
"http://sanaregistry.org/r/ndmxml/ndmxml-1.0-master.xsd"
id="CCSDS_RDM_VERS" version="1.0">
```

4.4.4 THE RDM/XML HEADER SECTION

4.4.4.1 The RDM header shall have a standard header format, with tags <header> and </header>.

4.4.4.2 Immediately following the <header> tag the message may have any number of <COMMENT></COMMENT> tag pairs.

4.4.4.3 The standard RDM header shall contain the following element tags:

- a) <CREATION_DATE>;
- b) <ORIGINATOR>;
- c) <MESSAGE_ID>.

NOTE – The rules for these keywords are specified in table 3-1. The header would look like this:

```
<header>
  <COMMENT>Some comment string.</COMMENT>
  <CREATION_DATE>2010-03-12T22:31:12.000</CREATION_DATE>
  <ORIGINATOR>AGENCYX</ORIGINATOR>
  <MESSAGE_ID>AGENCYX-1234</MESSAGE_ID>
</header>
```

4.4.5 THE RDM/XML BODY SECTION

4.4.5.1 After coding the <header>, the instantiation must include a <body></body> tag pair.

4.4.5.2 Inside the <body></body> tag pair must appear one <segment></segment> tag pair.

NOTE – In essence, the segment tag in the RDM XML implementation is not strictly necessary; however, it is necessary for structural symmetry with the overall NDM/XML paradigm (specified in reference [9], subsection 3.2).

4.4.5.3 The <segment> must be made up of one <metadata></metadata> tag pair and one <data></data> tag pair.

4.4.6 THE RDM/XML METADATA SECTION

4.4.6.1 The metadata section shall be set off by the <metadata></metadata> tag combination.

4.4.6.2 Between the <metadata> and </metadata> tags, the keywords shall be those specified in table 3-2.

4.4.6.3 Immediately following the <metadata> tag, the message may have any number of <COMMENT></COMMENT> tag pairs.

4.4.7 THE RDM DATA SECTION

4.4.7.1 The data section shall follow the metadata section and shall be set off by the <data></data> tag combination.

4.4.7.2 Between the <data> and </data> tags, the keywords shall be those specified in table 3-3.

4.4.7.3 Immediately following the <data> tag, the message may have any number of <COMMENT></COMMENT> tag pairs.

4.4.7.4 Immediately following the special tags listed in table 3-1, the message may have any number of <COMMENT></COMMENT> tag pairs.

4.4.8 SPECIAL RDM/XML TAGS

Special tags that are not necessary in the KVN implementation shall be used to encapsulate the information in the XML implementation of the RDM. The special tags indicating logical block divisions shall be those defined in table 4-1.

Table 4-1: Special RDM/XML Tags

Special Tag	Definition
<atmosphericReentryParameters>	Delineates the logical block for atmospheric re-entry parameters.
<groundImpactParameters>	Delineates the logical block for ground impact and burn-up data parameters, if they are used.
<stateVector>	Delineates the state vector components in the coordinate system specified in the metadata, if it is used.
<covarianceMatrix>	Delineates the 6x6 position/velocity covariance matrix, if it is used.
<spacecraftParameters>	Delineates the logical block containing object physical parameters, if they are used.
<odParameters>	Delineates the logical block containing orbit determination parameters, if they are used.
<userDefinedParameters>	Delineates the logical block containing user defined parameters, if they are used. NOTE – The use of <userDefinedParameters> is defined in reference [9], subsection 4.16

4.4.9 UNITS IN THE RDM/XML

The units in the RDM/XML shall be the same units used in the KVN-formatted RDM described in 3.4 and 3.5. XML attributes shall be used to explicitly define the units or other important information associated with the given data element (examples in annex D).

4.5 LOCAL OPERATIONS

4.5.1 For use in a local operations environment, the NDM/XML schema set (which includes the RDM schema) may be downloaded from the SANA Web site to a local server that meets local requirements for operations robustness (more details can be found in reference [9], paragraphs 4.3.4 and 4.3.5).

4.5.2 If a local version is used, the value associated with the xsi:noNamespaceSchemaLocation attribute must be changed to a URL that is accessible to the local server.

5 RE-ENTRY DATA MESSAGE DATA AND SYNTAX

5.1 OVERVIEW

This section details the syntax requirements for the RDM using both the KVN and XML formats.

5.2 COMMON RDM SYNTAX

5.2.1 OVERVIEW

This subsection details the syntax requirements that are common to both KVN and XML formats.

5.2.2 RDM LINES

5.2.2.1 Each RDM line must not exceed 254 ASCII characters and spaces (excluding line termination character[s]).

5.2.2.2 Only printable ASCII characters and blanks shall be used. Control characters (such as TAB, etc.) shall not be used, with the exception of the line termination characters specified below.

5.2.2.3 Blank lines may be used at any position within the file. Blank lines shall have no assignable meaning, and may be ignored.

5.2.2.4 All lines shall be terminated by a single Carriage Return or a single Line Feed, or a Carriage Return/Line Feed pair, or a Line Feed/Carriage Return pair.

5.2.3 RDM VALUES

5.2.3.1 A nonempty, valid value must be specified for each mandatory keyword.

5.2.3.2 Non-integer numeric values may be expressed in either fixed-point or floating-point notation.

5.2.3.3 Text value fields must be constructed using only all uppercase ('_', '-', blank spaces, and digits are permitted as well). An exception is made for comment values (comments are specified in 5.2.5).

5.2.3.4 Blanks shall not be permitted within numeric values and time strings.

5.2.4 RDM UNITS

5.2.4.1 If units are applicable, as specified in table 3-3, they must be displayed and they must exactly match the units specified in each table (including case; units conventions and operations are described in 1.5).

5.2.4.2 The notation ‘[n/a]’ shall not appear in an RDM as a units designator.

NOTE – Some of the items in table 3-3 are dimensionless (e.g., DRAG_COEFF). For such items, the table shows a unit value of ‘n/a’, which in this case means that there is no applicable units designator for those items.

5.2.5 RDM COMMENTS

5.2.5.1 Comment lines shall be optional in the RDM.

5.2.5.2 Comments shall be placed as specified in tables in section 3 describing the keywords. In the places where comments are allowed any number of comments may appear.

5.2.5.3 Comment text may be in any case desired by the user.

5.3 THE RDM IN KVN

5.3.1 OVERVIEW

KVN instantiations of an RDM shall observe the syntax described in 5.3.

5.3.2 RDM LINES IN KVN

5.3.2.1 Each RDM file shall consist of a set of RDM lines. Each RDM line shall be one of the following:

- Header line;
- Metadata line;
- Data line; or
- Blank line.

5.3.2.2 The first header line must be the first non-blank line in the file.

5.3.2.3 All header, metadata, and data lines shall use ‘keyword = value’ notation. For this purpose, only those keywords shown in tables 3-1, 3-2, and 3-3, shall be used in an RDM.

5.3.2.4 Only a single ‘keyword = value’ assignment shall be made on a line.

5.3.2.5 Keywords must be uppercase and must not contain blanks.

5.3.2.6 Any white space immediately preceding or following the keyword shall not be significant.

5.3.2.7 Any white space immediately preceding or following the 'equals' sign shall not be significant.

5.3.2.8 Any white space immediately preceding or following the units shall not be significant.

5.3.2.9 Any white space immediately preceding the end of line shall not be significant.

5.3.2.10 The order in which mandatory and optional KVN assignments appear shall be fixed as shown in the tables that describe the RDM keywords in section 3.

5.3.3 RDM VALUES IN KVN

5.3.3.1 Integer values shall consist of a sequence of decimal digits with an optional leading sign ('+' or '-'). If the sign is omitted, '+' shall be assumed. Leading zeroes may be used. The range of values that may be expressed as an integer is:

$$-2,147,483,648 \leq x \leq +2,147,483,647 \text{ (i.e., } -2^{31} \leq x \leq 2^{31} - 1)$$

NOTE – The commas in the range of values above are thousands separators and are used only for readability.

5.3.3.2 Non-integer numeric values expressed in fixed-point notation shall consist of a sequence of decimal digits separated by a period ('.') as a decimal point indicator, with an optional leading sign ('+' or '-'). If the sign is omitted, '+' shall be assumed. Leading and trailing zeroes may be used. At least one digit shall appear before and after a decimal point. The number of digits shall be 16 or fewer.

5.3.3.3 Non-integer numeric values expressed in floating point notation shall consist of a sign, a mantissa, an alphabetic character indicating the division between the mantissa and exponent, and an exponent, constructed according to the following rules:

- a) The sign may be '+' or '-'. If the sign is omitted, '+' shall be assumed.
- b) The mantissa must be a string of no more than 16 decimal digits with a decimal point ('.') in the second position of the ASCII string, separating the integer portion of the mantissa from the fractional part of the mantissa.
- c) The character used to denote exponentiation shall be 'E' or 'e'. If the character indicating the exponent and the following exponent are omitted, an exponent value of zero shall be assumed (yielding a fixed point value).

- d) The exponent must be an integer, and may have either a '+' or '-' sign; if the sign is omitted, then '+' shall be assumed.
- e) The maximum positive floating point value is approximately $1.798 \cdot 10^{308}$, with 16 significant decimal digits precision. The minimum positive floating point value is approximately $4.94 \cdot 10^{-324}$, with 16 significant decimal digits precision.

5.3.3.4 In value fields that are text, an underscore shall be equivalent to a single blank. Individual blanks shall be retained (shall be significant), but multiple contiguous blanks shall be equivalent to a single blank. This requirement does not apply to leading or trailing blanks, as per 5.3.2.7, 5.3.2.8, and 5.3.2.9.

5.3.3.5 In value fields representing a time tag or epoch, one of the following two formats shall be used:

yyyy-mm-ddT \mathbf{T} hh:mm:ss[.d→d][\mathbf{Z}]

or

yyyy-ddd \mathbf{T} hh:mm:ss[.d→d][\mathbf{Z}]

where 'yyyy' is the year, 'mm' is the two-digit month, 'dd' is the two-digit day of the month, and 'ddd' is the three-digit day of the year, separated by hyphens; ' \mathbf{T} ' is a fixed separator between the date and time portions of the string; and 'hh:mm:ss[.d→d]' is the time in hours, minutes, seconds, and fractional seconds, separated by colons. As many 'd' characters to the right of the period as required may be used to obtain the required precision, up to the maximum allowed for a fixed-point number. All fields require leading zeros. The format is specified in reference [10], subsection 3.5.

5.3.4 RDM UNITS IN KVN

When units are displayed:

- a) there must be at least one blank character between the value and the units;
- b) units shall be in the correct case (e.g., lowercase for km, uppercase for K or W; uppercase units are not used in the RDM), as indicated in table 3-3; and
- c) the units must be enclosed within square brackets (e.g., '[kg]').

5.3.5 RDM COMMENTS IN KVN

All comment lines shall begin with the 'COMMENT' keyword followed by at least one space. This keyword must appear on every comment line, not just the first such line. The remainder of the line shall be the comment value. White space shall be retained (shall be significant) in comment values.

5.4 THE RDM IN XML

5.4.1 OVERVIEW

XML instantiations of an RDM shall observe the syntax described in this subsection.

5.4.2 RDM LINES IN XML

Each RDM file shall consist of a set of RDM lines. Each RDM line shall be one of the following:

- XML version line;
- an XML-formatted line; or
- a blank line.

5.4.3 RDM VALUES IN XML

5.4.3.1 Each mandatory XML tag must be present and contain a valid value.

5.4.3.2 Integer values shall follow the conventions of the integer data type per reference [5], section 3.3.13. Additional restrictions on the allowable range of values permitted for any integer data element may also be defined in the RDM XML Schema.

NOTE – Examples of such restrictions may include a defined range (e.g., 0–100, 1–10), a set of enumerated values (e.g., 0, 1, 2, 4, 8), a pre-defined specific variation such as `positiveInteger`, or a user-defined data type variation.

5.4.3.3 Non-integer numeric values may be expressed in either fixed-point or floating-point notation. Numeric values shall follow the conventions of the double data type per reference [5], section 3.2.5. Additional restrictions on the allowable range of values permitted for any numeric data element may also be defined in the RDM XML Schema.

NOTE – Examples of such restrictions may include a defined range (e.g., 0.0–100.0), or a user-defined data type variation.

5.4.3.4 Text value data shall follow the conventions of the string data type per reference [5], section 3.2.1. Additional restrictions on the allowable range or values permitted for any data element may also be defined in the RDM XML Schema.

NOTE – Examples of such restrictions may include a set of enumerated values (e.g., ‘YES’/‘NO’) or other user-defined data type variation.

5.4.3.5 Text values in RDM/XML instantiations (i.e., the values between the opening and closing tags), shall consist of either all uppercase or all lowercase characters; an exception is made for values between the `<COMMENT>` and `</COMMENT>` tags, which may be in any

case desired by the user. Otherwise, mixing of uppercase and lowercase characters is prohibited.

5.4.3.6 In value fields that represent a time tag, values shall follow the conventions of the ndm: epochType data type used in all CCSDS NDM/XML schemas (as specified in 5.3.3.5).

5.4.4 RDM COMMENTS IN XML

Comments are optional and must be displayed as values between the <COMMENT> and </COMMENT> tags. Comments may be in any case desired by the user.

ANNEX A**IMPLEMENTATION CONFORMANCE STATEMENT (ICS)
PROFORMA****(NORMATIVE)****A1 INTRODUCTION****A1.1 OVERVIEW**

This annex provides the Implementation Conformance Statement (ICS) Requirements List (RL) for an implementation of a Re-entry Data Message. The ICS for an implementation is generated by completing the RL in accordance with the instructions below. An implementation claiming conformance must satisfy the mandatory requirements referenced in the RL.

A1.2 ABBREVIATIONS AND CONVENTIONS

The RL consists of information in tabular form. The status of features is indicated using the abbreviations and conventions described below.

Item Column

The item column contains sequential numbers for items in the table.

Feature Column

The feature column contains a brief descriptive name for a feature. It implicitly means ‘Is this feature supported by the implementation?’.

Status Column

The status column uses the following notations:

- M mandatory;
- optional;
- C conditional;
- X prohibited;
- I out of scope;
- N/A not applicable.

Support Column Symbols

The support column is to be used by the implementer to state whether a feature is supported by entering Y, N, or N/A, indicating:

- Y Yes, supported by the implementation.
- N No, not supported by the implementation.
- N/A Not applicable.

The support column should also be used, when appropriate, to enter values supported for a given capability.

A1.3 INSTRUCTIONS FOR COMPLETING THE RL

An implementer shows the extent of compliance to the RDM standard by completing the RL; that is, the state of compliance with all mandatory requirements and the options supported are shown. The resulting completed RL is called an ICS. The implementer shall complete the RL by entering appropriate responses in the support or values supported column, using the notation described in A1.2. If a conditional requirement is inapplicable, N/A should be used. If a mandatory requirement is not satisfied, exception information must be supplied by entering a reference X_i , where i is a unique identifier, to an accompanying rationale for the noncompliance.

A2 ICS PROFORMA FOR RDM

A2.1 GENERAL INFORMATION

A2.1.1 Identification of ICS

Date of Statement (DD/MM/YYYY)	
ICS serial number	
System Conformance statement cross-reference	

A2.1.2 Identification of Implementation Under Test

Implementation Name	
Implementation Version	
Special Configuration	
Other Information	

A2.1.3 Identification of Supplier

Supplier	
Contact Point for Queries	
Implementation Name(s) and Versions	
Other information necessary for full identification, e.g., name(s) and version(s) for machines and/or operating systems; System Name(s)	

A2.1.4 Identification of Specification

[CCSDS Document Number]	
Have any exceptions been required? NOTE – A YES answer means that the implementation does not conform to the Recommended Standard. Non-supported mandatory capabilities are to be identified in the ICS, with an explanation of why the implementation is non-conforming.	Yes [] No []

A2.2 REQUIREMENTS LIST

	Feature	Keyword	Reference	Status	Support
1	RDM Header	N/A	table 3-1	M	
2	RDM version	CCSDS_RDM_VERS	table 3-1	M	
3	Comment	COMMENT	table 3-1	O	
4	Message creation date/time	CREATION_DATE	table 3-1	M	
5	Message originator	ORIGINATOR	table 3-1	M	
6	Unique message identifier	MESSAGE_ID	table 3-1	M	
7	RDM Metadata	N/A	table 3-2	M	
8	Comment	COMMENT	table 3-2	O	
9	General information about the re-entering object	N/A	table 3-2	M	
10	Spacecraft name	OBJECT_NAME	table 3-2	M	
11	Spacecraft international designator	INTERNATIONAL_DESIGNATOR	table 3-2	M	
12	Object catalogue used	CATALOG_NAME	table 3-2	O	
13	Spacecraft ID in the catalogue	OBJECT_DESIGNATOR	table 3-2	O	
14	Spacecraft type	OBJECT_TYPE	table 3-2	O	
15	Spacecraft owner	OBJECT_OWNER	table 3-2	O	
16	Spacecraft operator	OBJECT_OPERATOR	table 3-2	O	

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

	Feature	Keyword	Reference	Status	Support
17	Controlled re-entry	CONTROLLED_REENTRY	table 3-2	M	
18	Celestial body orbited by the object	CENTER_NAME	table 3-2	M	
19	Time system user for the data in the metadata and data sections	TIME_SYSTEM	table 3-2	M	
20	Reference epoch to which orbit lifetime is computed	EPOCH_TZERO	table 3-2	M	
21	Information about any provided orbit data for the object/spacecraft	N/A	table 3-2	O	
22	Reference frame	REF_FRAME	table 3-2	O	
23	Reference frame epoch	REF_FRAME_EPOCH	table 3-2	O	
24	External ephemeris file identifier	EPHEMERIS_NAME	table 3-2	O	
25	Information about the orbit propagator used for re-entry prediction and orbit determination	N/A	table 3-2	O	
26	gravity model used	GRAVITY_MODEL	table 3-2	O	
27	atmospheric model used	ATMOSPHERIC_MODEL	table 3-2	O	
28	method used to estimate the solar flux indices for the atmospheric model	SOLAR_FLUX_PREDICTION	table 3-2	O	
29	n-body perturbations considered	N_BODY_PERTURBATIONS	table 3-2	O	
30	solar rad pressure	SOLAR_RAD_PRESSURE	table 3-2	O	
31	Earth tides	EARTH_TIDES	table 3-2	O	
32	any thrust from the spacecraft	INTRACK_THRUST	table 3-2	O	
33	any accounting for break-up and demise	REENTRY_DISINTEGRATION	table 3-2	O	
34	method used to determine the uncertainty in the ground impact location	IMPACT_UNCERTAINTY_METHOD	table 3-2	O	
35	Previous and next related RDM	N/A	table 3-2	O	
36	Identifier of the previous RDM	PREVIOUS_MESSAGE_ID	table 3-2	O	
37	Epoch of the previous RDM (predicted)	PREVIOUS_MESSAGE_EPOCH	table 3-2	O	
38	Time at which the next RDM will be issued (predicted)	NEXT_MESSAGE_EPOCH	table 3-2	O	
39	RDM Data	N/A	table 3-3	M	
40	Atmospheric re-entry information	N/A	table 3-3	M	

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

	Feature	Keyword	Reference	Status	Support
41	Comment	COMMENT	table 3-3	O	
42	Remaining orbit lifetime	ORBIT_LIFETIME	table 3-3	M	
43	Dispersion of remaining orbit lifetime	LIFETIME_DISPERSION	table 3-3	O	
44	Defined re-entry altitude	REENTRY_ALTITUDE	table 3-3	M	
45	Predicted re-entry epoch	NOMINAL_REENTRY_EPOCH	table 3-3	O	
46	Re-entry window	REENTRY_WINDOW_START	table 3-3	O	
47		REENTRY_WINDOW_END	table 3-3	O	
48	Ground impact information	N/A	table 3-3	O	
49	Comment	COMMENT	table 3-3	O	
50	Probability any re-entry fragments reach the Earth surface	PROBABILITY_OF_IMPACT	table 3-3	O	
51	Probability all re-entry fragments suffer total demise	PROBABILITY_OF_BURN_UP	table 3-3	O	
52	Probability fragments are generated during re-entry	PROBABILITY_OF_BREAK_UP	table 3-3	O	
53	Land impact probability	PROBABILITY_OF_LAND_IMPACT	table 3-3	O	
54	Probabilities of casualties resulting from the re-entry	PROBABILITY_OF_CASUALTY	table 3-3	O	
55	Predicted (ground) impact epoch	NOMINAL_IMPACT_EPOCH	table 3-3	O	
56	Predicted (ground) impact window	IMPACT_WINDOW_START	table 3-3	O	
57		IMPACT_WINDOW_END	table 3-3	O	
58	Reference frame of (ground) impact location	IMPACT_REF_FRAME	table 3-3	O	
59	Impact location	NOMINAL_IMPACT_LON	table 3-3	O	
60		NOMINAL_IMPACT_LAT	table 3-3	O	
61		NOMINAL_IMPACT_ALT	table 3-3	O	
62	Impact dispersion	IMPACT_1_CONFIDENCE	table 3-3	O	
63		IMPACT_1_START_LON	table 3-3	O	
64		IMPACT_1_START_LAT	table 3-3	O	
65		IMPACT_1_STOP_LON	table 3-3	O	
66		IMPACT_1_STOP_LAT	table 3-3	O	
67		IMPACT_1_CROSS_TRACK	table 3-3	O	
68		IMPACT_2_CONFIDENCE	table 3-3	O	
69		IMPACT_2_START_LON	table 3-3	O	
70		IMPACT_2_START_LAT	table 3-3	O	
71		IMPACT_2_STOP_LON	table 3-3	O	
72		IMPACT_2_STOP_LAT	table 3-3	O	
73		IMPACT_2_CROSS_TRACK	table 3-3	O	
74		IMPACT_3_CONFIDENCE	table 3-3	O	

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

	Feature	Keyword	Reference	Status	Support
75		IMPACT_3_START_LON	table 3-3	O	
76		IMPACT_3_START_LAT	table 3-3	O	
77		IMPACT_3_STOP_LON	table 3-3	O	
78		IMPACT_3_STOP_LAT	table 3-3	O	
79		IMPACT_3_CROSS_TRACK	table 3-3	O	
80	Spacecraft state vector section	N/A	table 3-3	O	
81	Comment	COMMENT	table 3-3	O	
82	State vector epoch	EPOCH	table 3-3	O	
83	Position and velocity vectors	X	table 3-3	O	
84		Y	table 3-3	O	
85		Z	table 3-3	O	
86		X_DOT	table 3-3	O	
87		Y_DOT	table 3-3	O	
88		Z_DOT	table 3-3	O	
89	Spacecraft state vector covariance information	N/A	table 3-3	O	
90	Comment	COMMENT	table 3-3	O	
91	Covariance reference frame	COV_REF_FRAME	table 3-3	O	
92	6x6 position/velocity covariance matrix elements	CX_X	table 3-3	O	
93		CY_X	table 3-3	O	
94		CY_Y	table 3-3	O	
95		CZ_X	table 3-3	O	
96		CZ_Y	table 3-3	O	
97		CZ_Z	table 3-3	O	
98		CX_DOT_X	table 3-3	O	
99		CX_DOT_Y	table 3-3	O	
100		CX_DOT_Z	table 3-3	O	
101		CX_DOT_X_DOT	table 3-3	O	
102		CY_DOT_X	table 3-3	O	
103		CY_DOT_Y	table 3-3	O	
104		CY_DOT_Z	table 3-3	O	
105		CY_DOT_X_DOT	table 3-3	O	
106		CY_DOT_Y_DOT	table 3-3	O	
107	CZ_DOT_X	table 3-3	O		
108	CZ_DOT_Y	table 3-3	O		
109	CZ_DOT_Z	table 3-3	O		
110	CZ_DOT_X_DOT	table 3-3	O		
111	CZ_DOT_Y_DOT	table 3-3	O		
112	CZ_DOT_Z_DOT	table 3-3	O		
113	Spacecraft properties	N/A	table 3-3	O	
114	Comments	COMMENT	table 3-3	O	
115	Mass	MASS	table 3-3	O	
116	Solar radiation area	SOLAR_RAD_AREA	table 3-3	O	

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

	Feature	Keyword	Reference	Status	Support
117	Solar radiation coefficient	SOLAR_RAD_COEFF	table 3-3	O	
118	Drag area	DRAG_AREA	table 3-3	O	
119	Coefficient of drag	DRAG_COEFF	table 3-3	O	
120	Radar Cross-Section	RCS	table 3-3	O	
121	Ballistic coefficient	BALLISTIC_COEFF	table 3-3	O	
122	Object's acceleration used in OD and propagation	THRUST_ACCELERATION	table 3-3	O	
123	Orbit determination information	N/A	table 3-3	O	
124	Comment	COMMENT	table 3-3	O	
125	Interval during which the last accepted observation occurred	TIME_LASTOBS_START	table 3-3	O	
126		TIME_LASTOBS_END	table 3-3	O	
127	Recommend timespan for OD and actual timespan used	RECOMMENDED_OD_SPAN	table 3-3	O	
128		ACTUAL_OD_SPAN	table 3-3	O	
129	Total number of observations available and used	OBS_AVAILABLE	table 3-3	O	
130		OBS_USED	table 3-3	O	
131	Total number of sensor tracks available and used	TRACKS_AVAILABLE	table 3-3	O	
132		TRACKS_USED	table 3-3	O	
133	Percentage of residuals accepted in OD	RESIDUALS_ACCEPTED	table 3-3	O	
134	Weighted RMS of the OD residuals	WEIGHTED_RMS	table 3-3	O	
135	User defined parameters	USER_DEFINED_x Any supported user defined parameters should be listed here.	table 3-3	O	

ANNEX B**VALUES FOR TIME_SYSTEM AND FRAME RELATED KEYWORDS****(NORMATIVE)**

The values in this annex represent the set of acceptable values for the TIME_SYSTEM, REF_FRAME, COV_REF_FRAME, and IMPACT_REF_FRAME keywords in the RDM. The *Navigation Data—Definitions and Conventions* Green Book (reference [I1]) contains more details about the meaning of the values.

B1 TIME_SYSTEM METADATA KEYWORD

TIME_SYSTEM Value	Meaning
GALILEO	Galileo System Time
GMST	Greenwich Mean Sidereal Time
GPS	Global Positioning System (time)
TAI	International Atomic Time
TCB	Barycentric Coordinate Time
TCG	Geocentric Coordinate Time
TDB	Barycentric Dynamical Time
TT	Terrestrial Time
UT1	Universal Time
UTC	Coordinated Universal Time

B2 REF_FRAME METADATA KEYWORD

REF_FRAME Value	Meaning
EME2000	Earth Mean Equator and Equinox of J2000
GCRF	Geocentric Celestial Reference Frame
GRC	Greenwich Rotating Coordinates
ICRF	International Celestial Reference Frame
ITRFYYYY	International Terrestrial Reference Frame yyyy, where yyyy is the version (e.g., ITRF2014, ITRF2008, ITRF97)
MCI	Mars Centered Inertial
TDR	True of Date, Rotating
TOD	True of Date

B3 COV_REF_FRAME DATA KEYWORD

COV_REF_FRAME Value	Meaning
RSW	Another name for 'Radial, Transverse, Normal'
RTN	Radial, Transverse, Normal
TNW	A local orbital coordinate frame that has the T-axis along the velocity vector, W along the orbital angular momentum vector, and N completes the right handed system

B4 IMPACT_REF_FRAME DATA KEYWORD

IMPACT_REF_FRAME Value	Meaning
GTRF	Galileo Terrestrial Reference Frame
ITRFyyyy	International Terrestrial Reference Frame yyyy, where yyyy is the version (e.g., ITRF2014, ITRF2008, ITRF97)
MARS2000	Mars 2000 Geographic Coordinate System
WGS84	World Geodetic System 84

ANNEX C

SECURITY, SANA, AND PATENT CONSIDERATIONS

(INFORMATIVE)

C1 SECURITY CONSIDERATIONS

This subsection presents the results of an analysis of security considerations applied to the technologies specified in this Recommended Standard.

C1.1 SECURITY CONCERNS WITH RESPECT TO THE CCSDS DOCUMENT

C1.1.1 Data Privacy

Privacy of data formatted in compliance with the specifications of this Recommended Standard should be assured by the systems and networks on which this Recommended Standard is implemented.

C1.1.2 Data Integrity

Integrity of data formatted in compliance with the specifications of this Recommended Standard should be assured by the systems and networks on which this Recommended Standard is implemented.

C1.1.3 Authentication of Communicating Entities

Authentication of communicating entities involved in the transport of data which complies with the specifications of this Recommended Standard should be provided by the systems and networks on which this Recommended Standard is implemented.

C1.1.4 Control of Access to Resources

Control of access to resources should be managed by the systems upon which originator formatting and recipient processing are performed.

C1.1.5 Auditing of Resource Usage

Auditing of resource usage should be handled by the management of systems and networks on which this Recommended Standard is implemented.

C1.2 POTENTIAL THREATS AND ATTACK SCENARIOS

Potential threats or attack scenarios include, but are not limited to, (a) unauthorized access to the programs/processes that generate and interpret the messages, (b) unauthorized access to the messages during transmission between exchange partners, and (c) modification of the messages between partners. Protection from unauthorized access during transmission is especially important if the RDM provider and users utilize open ground networks, such as the Internet, to exchange data formatted in compliance with this Recommended Standard. It is strongly recommended that potential threats or attack scenarios applicable to the systems and networks on which this Recommended Standard is implemented be addressed by the management of those systems and networks.

C1.3 CONSEQUENCES OF NOT APPLYING SECURITY TO THE TECHNOLOGY

The consequences of not applying security to the systems and networks on which this Recommended Standard is implemented could include potential loss, corruption, and theft of data. The orbit data included in the RDM could allow an unintended recipient to track a re-entering spacecraft, and the ground impact data could allow them to collect any debris in an unauthorized fashion.

C2 SANA CONSIDERATIONS

The following RDM related items will be registered with the SANA Operator:

- The RDM XML schemas.

The following RDM elements should be taken from the appropriate SANA registry:

- The RDM originator should be taken from the SANA Organizations registry;
- The catalog name should be taken from the SANA CDM catalog name registry.

The registration rule for new entries in the registry is the approval of new requests by the CCSDS Area or Working Group responsible for the maintenance of the RDM at the time of the request. New requests for this registry should be sent to SANA (info@sanaregistry.org).

C3 PATENT CONSIDERATIONS

The recommendations of this Recommended Standard have no patent issues.

ANNEX D

RE-ENTRY DATA MESSAGE EXAMPLES

(INFORMATIVE)

Figures D-1 and D-2 show examples of RDM messages in KVN. The former only includes mandatory keywords, while the latter uses optional keywords. Figure D-1 presents a very basic RDM, the kind a Member Agency (or any other group) would make available to the interested public (e.g., amateur astronomers wishing to observe a re-entry) for long-term re-entry prediction and containing only the remaining orbital lifetime. Figure D-2 shows a more complex message, containing the state vector, position/velocity covariance matrix, the kind of information two Member Agencies might exchange with each other for short-term re-entry predictions.

CCSDS_RDM_VERS	= 1.0		
CREATION_DATE	= 2018-04-22T09:31:34.00		
ORIGINATOR	= ESA		
MESSAGE_ID	= ESA/20180422-001		
OBJECT_NAME	= SPACEOBJECT		
INTERNATIONAL_DESIGNATOR	= 2018-099B		
CONTROLLED_REENTRY	= NO		
CENTER_NAME	= EARTH		
TIME_SYSTEM	= UTC		
EPOCH_TZERO	= 2018-04-22T00:00:00.00		
ORBIT_LIFETIME	= 23.0	[d]	
REENTRY_ALTITUDE	= 150.0		[km]

Figure D-1: Sample RDM in KVN Using Only Mandatory Keywords

CCSDS_RDM_VERS	= 1.0		
CREATION_DATE	= 2018-04-22T09:31:34.00		
ORIGINATOR	= ESA		
MESSAGE_ID	= ESA/20180422-001		
OBJECT_NAME	= SPACEOBJECT		
INTERNATIONAL_DESIGNATOR	= 2018-099B		
CATALOG_NAME	= SATCAT		
OBJECT_DESIGNATOR	= 81594		
OBJECT_TYPE	= ROCKET BODY		
OBJECT_OWNER	= ESA		
CONTROLLED_REENTRY	= NO		
CENTER_NAME	= EARTH		
TIME_SYSTEM	= UTC		
EPOCH_TZERO	= 2018-04-22T09:00:00.00		
REF_FRAME	= EME2000		
GRAVITY_MODEL	= EGM-96: 36D 360		
ATMOSPHERIC_MODEL	= NRLMSISE-00		
N_BODY_PERTURBATIONS	= MOON		
SOLAR_RAD_PRESSURE	= NO		

Figure D-2: Sample RDM in KVN Using Optional Keywords

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

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EARTH_TIDES = ESR
INTRACK_THRUST = NO
RE_ENTRY_DISINTEGRATION = MASS-LOSS + BREAK-UP
PREVIOUS_MESSAGE_ID = ESA/20180421-007
NEXT_MESSAGE_EPOCH = 2018-04-23T09:00:00

COMMENT Short term re-entry prediction results
ORBIT_LIFETIME = 5.5 [d]
REENTRY_ALTITUDE = 80.0 [km]
REENTRY_WINDOW_START = 2018-04-27T11:45:33
REENTRY_WINDOW_END = 2018-04-27T22:12:56

PROBABILITY_OF_IMPACT = 0.0
PROBABILITY_OF_BURN_UP = 1.0

COMMENT State vector at the last OD epoch
EPOCH = 2018-04-22T09:30:12
X = 4000.000000 [km]
Y = 4000.000000 [km]
Z = 4000.000000 [km]
X_DOT = 7.000000 [km/s]
Y_DOT = 7.000000 [km/s]
Z_DOT = 7.000000 [km/s]

COMMENT Position/velocity covariance matrix at last OD epoch
COV_REF_FRAME = RTN
CX_X = 0.10000 [km**2]
CY_X = 0.10000 [km**2]
CY_Y = 0.10000 [km**2]
CZ_X = 0.10000 [km**2]
CZ_Y = 0.10000 [km**2]
CZ_Z = 0.10000 [km**2]
CX_DOT_X = 0.02000 [km**2/s]
CX_DOT_Y = 0.02000 [km**2/s]
CX_DOT_Z = 0.02000 [km**2/s]
CX_DOT_X_DOT = 0.00500 [km**2/s**2]
CY_DOT_X = 0.02000 [km**2/s]
CY_DOT_Y = 0.02000 [km**2/s]
CY_DOT_Z = 0.02000 [km**2/s]
CY_DOT_X_DOT = 0.00600 [km**2/s**2]
CY_DOT_Y_DOT = 0.00600 [km**2/s**2]
CZ_DOT_X = 0.02000 [km**2/s]
CZ_DOT_Y = 0.02000 [km**2/s]
CZ_DOT_Z = 0.02000 [km**2/s]
CZ_DOT_X_DOT = 0.00400 [km**2/s**2]
CZ_DOT_Y_DOT = 0.00400 [km**2/s**2]
CZ_DOT_Z_DOT = 0.00400 [km**2/s**2]

COMMENT Spacecraft parameters used in OD and re-entry prediction
MASS = 3582 [kg]
DRAG_AREA = 23.3565 [m**2]
DRAG_COEFF = 2.2634

COMMENT OD parameters from batch orbit determination
ACTUAL_OD_SPAN = 3.4554 [d]
OBS_AVAILABLE = 137
OBS_USED = 129
TRACKS_AVAILABLE = 18
TRACKS_USED = 17

```

Figure D-2: Sample RDM in KVN Using Optional Keywords (Continued)

Figures D-3 and D-4 show examples of RDM messages in the XML format. Some of the lines wrap in this representation, but would not wrap in an actual RDM file given the 254 character line length.

```
<?xml version="1.0" encoding="UTF-8"?>
<rdm
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:noNamespaceSchemaLocation="http://sanaregistry.org/r/ndmxml/ndmxml-1.0-
  master.xsd" id="CCSDS_RDM_VERS" version="1.0">
  <header>
    <COMMENT>This is RDM Annex C KVN Fig C-1 expressed in XML</COMMENT>
    <CREATION_DATE>2018-04-22T09:31:34</CREATION_DATE>
    <ORIGINATOR>ESA</ORIGINATOR>
    <MESSAGE_ID>ESA/20180422-001</MESSAGE_ID>
  </header>
  <body>
    <segment>
      <metadata>
        <OBJECT_NAME>SPACEOBJECT</OBJECT_NAME>
        <INTERNATIONAL_DESIGNATOR>2018-099B</INTERNATIONAL_DESIGNATOR>
        <OBJECT_TYPE>ROCKET BODY</OBJECT_TYPE>
        <CONTROLLED_REENTRY>NO</CONTROLLED_REENTRY>
        <CENTER_NAME>EARTH</CENTER_NAME>
        <TIME_SYSTEM>UTC</TIME_SYSTEM>
        <EPOCH_TZERO>2018-04-22T00:00:00.00</EPOCH_TZERO>
      </metadata>
      <data>
        <atmosphericReentryParameters>
          <ORBIT_LIFETIME units="d">23.0</ORBIT_LIFETIME>
          <REENTRY_ALTITUDE units="km">150.0</REENTRY_ALTITUDE>
        </atmosphericReentryParameters>
      </data>
    </segment>
  </body>
</rdm>
```

Figure D-3: Sample RDM in XML Using Only Mandatory Keywords

```
<?xml version="1.0" encoding="UTF-8"?>
<rdm xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xsi:noNamespaceSchemaLocation="file:///Z:/Desktop/ccsds-ndmxml/schemas-
  TESTunqual/ndmxml-1.0-master.xsd" id="CCSDS_RDM_VERS" version="1.0">
  <header>
    <COMMENT>This is RDM Annex C KVN Fig C-2 expressed in XML</COMMENT>
    <CREATION_DATE>2018-04-22T09:31:34</CREATION_DATE>
    <ORIGINATOR>ESA</ORIGINATOR>
    <MESSAGE_ID>ESA/20180422-001</MESSAGE_ID>
  </header>
  <body>
    <segment>
      <metadata>
        <OBJECT_NAME>SPACEOBJECT</OBJECT_NAME>
        <INTERNATIONAL_DESIGNATOR>2018-099B</INTERNATIONAL_DESIGNATOR>
        <CATALOG_NAME>SATCAT</CATALOG_NAME>
        <OBJECT_DESIGNATOR>81594</OBJECT_DESIGNATOR>
      </metadata>
    </segment>
  </body>
</rdm>
```

Figure D-4: Sample RDM in XML Using Optional Keywords

```

<OBJECT_TYPE>ROCKET BODY</OBJECT_TYPE>
<OBJECT_OWNER>ESA</OBJECT_OWNER>
<CONTROLLED_REENTRY>NO</CONTROLLED_REENTRY>
<CENTER_NAME>EARTH</CENTER_NAME>
<TIME_SYSTEM>UTC</TIME_SYSTEM>
<EPOCH_TZERO>2018-04-22T00:00:00.00</EPOCH_TZERO>
<REF_FRAME>EME2000</REF_FRAME>
<GRAVITY_MODEL>EGM-96: 36D 360</GRAVITY_MODEL>
<ATMOSPHERIC_MODEL>NRLMSISE-00</ATMOSPHERIC_MODEL>
<N_BODY_PERTURBATIONS>MOON</N_BODY_PERTURBATIONS>
<SOLAR_RAD_PRESSURE>NO</SOLAR_RAD_PRESSURE>
<EARTH_TIDES>ESR</EARTH_TIDES>
<INTRACK_THRUST>NO</INTRACK_THRUST>
<REENTRY_DISINTEGRATION>MASS-LOSS + BREAK-
UP</REENTRY_DISINTEGRATION>
<PREVIOUS_MESSAGE_ID>ESTEC/20150421-007</PREVIOUS_MESSAGE_ID>
<PREVIOUS_MESSAGE_EPOCH>2015-04-
23T09:00:00</PREVIOUS_MESSAGE_EPOCH>
</metadata>
<data>
  <atmosphericReentryParameters>
    <ORBIT_LIFETIME units="d">5.5</ORBIT_LIFETIME>
    <REENTRY_ALTITUDE units="km">80.0</REENTRY_ALTITUDE>
    <REENTRY_WINDOW_START>2018-04-
27T11:45:33</REENTRY_WINDOW_START>
    <REENTRY_WINDOW_END>2018-04-27T22:12:56</REENTRY_WINDOW_END>
  </atmosphericReentryParameters>

  <groundImpactParameters>
    <COMMENT>Short term re-entry prediction results</COMMENT>
    <PROBABILITY_OF_IMPACT>0.0</PROBABILITY_OF_IMPACT>
    <PROBABILITY_OF_BURN_UP>1.0</PROBABILITY_OF_BURN_UP>
  </groundImpactParameters>

  <stateVector>
    <COMMENT>State vector at the last OD epoch</COMMENT>
    <EPOCH>2018-04-22T09:30:12</EPOCH>
    <X units="km">4000.000000</X>
    <Y units="km">4000.000000</Y>
    <Z units="km">4000.000000</Z>
    <X_DOT units="km/s">7.000000</X_DOT>
    <Y_DOT units="km/s">7.000000</Y_DOT>
    <Z_DOT units="km/s">7.000000</Z_DOT>
  </stateVector>

  <covarianceMatrix>
    <COMMENT>Position/velocity covariance matrix at last OD
epoch</COMMENT>
    <COV_REF_FRAME>RTN</COV_REF_FRAME>
    <CX_X units="km**2">0.10000</CX_X>
    <CY_X units="km**2">0.10000</CY_X>
    <CY_Y units="km**2">0.10000</CY_Y>
    <CZ_X> units="km**2">0.10000</CZ_X>
    <CZ_Y> units="km**2">0.10000</CZ_Y>
    <CZ_Z units="km**2">0.10000</CZ_Z>
    <CX_DOT_X units="km**2/s">0.20000</CX_DOT_X>
    <CX_DOT_Y units="km**2/s">0.20000</CX_DOT_Y>

```

Figure D-4: Sample RDM in XML Using Optional Keywords (Continued)

```

    <CX_DOT_Z units="km**2/s">0.20000</CX_DOT_Z>
    <CX_DOT_X_DOT units="km**2/s**2">0.00500</CX_DOT_X_DOT>
    <CY_DOT_X units="km**2/s">0.20000</CY_DOT_X>
    <CY_DOT_Y units="km**2/s">0.20000</CY_DOT_Y>
    <CY_DOT_Z units="km**2/s">0.20000</CY_DOT_Z>
    <CY_DOT_X_DOT units="km**2/s**2">0.00600</CY_DOT_X_DOT>
    <CY_DOT_Y_DOT units="km**2/s**2">0.00600</CY_DOT_Y_DOT>
    <CZ_DOT_X units="km**2/s">0.00200</CZ_DOT_X>
    <CZ_DOT_Y units="km**2/s">0.00200</CZ_DOT_Y>
    <CZ_DOT_Z units="km**2/s">0.00200</CZ_DOT_Z>
    <CZ_DOT_X_DOT units="km**2/s**2">0.00400</CZ_DOT_X_DOT>
    <CZ_DOT_Y_DOT units="km**2/s**2">0.00400</CZ_DOT_Y_DOT>
    <CZ_DOT_Z_DOT units="km**2/s**2">0.00400</CZ_DOT_Z_DOT>
  </covarianceMatrix>

  <spacecraftParameters>
    <COMMENT>Spacecraft parameters used in OD and re-entry
prediction</COMMENT>
    <MASS>3582</MASS>
    <DRAG_AREA>23.3565</DRAG_AREA>
    <DRAG_COEFF>2.2634</DRAG_COEFF>
  </spacecraftParameters>

  <odParameters>
    <COMMENT>Object1 OD Parameters</COMMENT>
    <ACTUAL_OD_SPAN units="d">3.4554</ACTUAL_OD_SPAN>
    <OBS_AVAILABLE>137</OBS_AVAILABLE>
    <OBS_USED>129</OBS_USED>
    <TRACKS_AVAILABLE>18</TRACKS_AVAILABLE>
    <TRACKS_USED>17</TRACKS_USED>
  </odParameters>
</data>
</segment>
</body>
</rdm>

```

Figure D-4: Sample RDM in XML Using Optional Keywords (Continued)

ANNEX E**ABBREVIATIONS AND ACRONYMS****(INFORMATIVE)**

ASCII	American Standard Code for Information Interchange
CCSDS	Consultative Committee for Space Data Systems
COSPAR	Committee on Space Research
CDM	Conjunction Data Message
ICD	Interface Control Document
ICS	Implementation Conformance Statement
ID	IDentifier
ISO	International Organization for Standardization
KVN	Keyword Value Notation
NDM	Navigation Data Message
OD	Orbit Determination
OEM	Orbit Ephemeris Message
ODM	Orbit Data Message
OPM	Orbit Parameter Message
PDF	Probability Distribution Function
RDM	Re-entry Data Message
RL	Requirements List
SANA	Space Assigned Numbers Authority
SI	International System of Units
SRP	Solar Radiation Pressure
SSA	Space Situational Awareness
SST	Space Surveillance and Tracking
UN OOSA	United Nations Office for Outer Space Affairs
UTC	Coordinated Universal Time
XML	eXtensible Markup Language

ANNEX F

RATIONALE AND REQUIREMENTS FOR RE-ENTRY DATA MESSAGES

(INFORMATIVE)

This annex presents the rationale and requirements behind the design of the Re-entry Data Message. Table F-1 shows the RDM requirements’:

- requirement identifier;
- requirement text;
- rationale behind the requirement;
- traceability to sections of this standard; and
- whether the requirement is mandatory (M) (shall) or optional (O), but desirable (should).

Table F-1: RDM Requirements and Rationale

#	Requirement	Rationale	Trace	M/O
RDM-0010	The RDM shall be provided in digital form.	To facilitate automated interaction.	3.2.2	M
RDM-0020	The RDM shall be provided in platform-independent data structures.	The CCSDS objective of promoting interoperability is best met by avoiding proprietary data formats.	section 3	M
RDM-0025	The RDM shall be readable by both humans and computers.	To facilitate both automatic interaction and analysis of the data by human operators.	table 3-1 table 3-2 table 3-3	M
RDM-0030	The RDM shall provide a means of uniquely identifying each message.	The file name is not sufficient for these purposes and a unique ID facilitates exchange.	table 3-1	M
RDM-0040	The RDM shall clearly identify the object predicted to (re)enter.	Any ambiguity in the object reduces the usefulness of the message.	table 3-2	M
RDM-0050	The RDM shall provide the remaining orbit lifetime of the object.	This information is needed to determine the timeliness of any needed mitigation measures.	table 3-3	M
RDM-0055	The RDM shall specify whether the re-entry is controlled, uncontrolled or unknown.	To determine if/what mitigation measures are needed. Unknown is a valid value as well.	table 3-2	M
RDM-0060	The RDM shall provide time measurements in the accepted CCSDS timecode formats.	To fulfill the CCSDS’ objective of promoting interoperability and to make them easier to read and understand by humans.	table 3-2	M

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

#	Requirement	Rationale	Trace	M/O
RDM-0070	The RDM shall provide the units used for all the measurements.	To promote interoperability and eliminate ambiguity.	table 3-3	M
RDM-0080	The RDM shall allow the exchange of (re-)entry information for objects orbiting an arbitrary body.	Allows the use of the standard for Moon/Mars/Jupiter atmospheric entry besides Earth, further promoting the use of this standard.	table 3-2	M
RDM-0090	The information in the RDM shall be usable without the need to model any (re-)entry spacecraft dynamics by the receiving entity.	There are several situations in which this is useful, such as remaining orbit lifetime is too short for modeling or the receiving entity does not have those capabilities.	table 3-3	M
RDM-0100	The RDM should be extensible, without disrupting existing uses.	Some users might need other parameters and they should be able to use them with user defined lines specified in an ICD.	table 3-1 table 3-3	O
RDM-0110	The RDM should be consistent with the other CCSDS messages.	To facilitate use and improve readability.	table 3-2	O
RDM-0120	The RDM shall allow for the object owner/operator to be specified.	Can help with mitigation measures.	table 3-2	M
RDM-0130	The RDM should allow the exchange of one spacecraft position/velocity state vector and associated information.	Allows the message to be self-contained and not rely on ODMs (which might require an ICD).	table 3-3	O
RDM-0140	The RDM should allow the exchange of covariance information for the position/velocity state vector.	To allow the uncertainty in the state vector to be exchanged as well.	table 3-3	O
RDM-0150	The RDM should allow the modeling used to determine the data to be specified.	Necessary if the data is to be verified by the received agency.	table 3-2	O
RDM-0160	The RDM shall contain information about the previous and next messages for the same spacecraft.	Because of modeling uncertainties it is expected that RDMs for the same spacecraft would be published regularly.	table 3-2	M
RDM-0170	The RDM shall specify the predicted ground impact location and epoch for the object.	Important information if ground impact is predicted.	table 3-3	M
RDM-0180	The RDM should contain the spacecraft parameters used in OD and re-entry prediction.	Allows verification and independent orbit propagation.	table 3-3	O
RDM-0190	The RDM shall contain information about the observations used in OD.	Allows the receiving agency to evaluate how reliable is the data.	table 3-3	M

ANNEX G

RDM SUMMARY SHEET

(INFORMATIVE)

The provision of optional keywords is at the discretion of the data provider. This annex is intended to provide a helpful guide (table G-1) in associating optional metadata keywords (from table 3-2) and data categories (from table 3-3). There are only a few required metadata and data keywords, but many more that are applicable to one or more data categories. Some data categories can also provide extra information for other categories. Additionally, there are some keywords that are only applicable in certain restricted situations. Finally, there are some metadata keywords that are completely optional. This summary may assist the user in constructing an RDM that properly describes a specific re-entry event.

The terms ‘required’ and ‘recommended’ in table G-1 relate only to the context set by the data categories and are not normative for the RDM.

Table G-1: Relationship between RDM Data Categories and Optional Metadata Keywords

Data category	Relevant metadata optional keywords	Relevant data blocks
long-term atmospheric re-entry	required: none	required: none (only mandatory keywords)
	recommended: GRAVITY_MODEL ATMOSPHERIC_MODEL SOLAR_FLUX_PREDICTION N_BODY_PERTURBATIONS	recommended: spacecraft parameters
short-term atmospheric re-entry	required: none	required: none
	recommended: GRAVITY_MODEL ATMOSPHERIC_MODEL SOLAR_FLUX_PREDICTION N_BODY_PERTURBATIONS	recommended: NOMINAL_REENTRY_EPOCH REENTRY_WINDOW_START REENTRY_WINDOW_END spacecraft parameters
ground impact data	required: RE_ENTRY_DISINTEGRATION	required: ground impact and burn-up data
	recommended: same as short-term atmospheric re-entry, and: IMPACT_UNCERTAINTY_METHOD	recommended: same as short-term atmospheric re-entry
object state vector	required: REF_FRAME	required: none
		recommended: spacecraft parameters
position/velocity covariance matrix	required: none	required: object state vector
spacecraft parameters	required: none	required: none

CCSDS DRAFT RECOMMENDED STANDARD FOR RE-ENTRY DATA MESSAGE

Data category	Relevant metadata optional keywords	Relevant data blocks
orbit determination parameters	required: GRAVITY_MODEL ATMOSPHERIC_MODEL SOLAR_FLUX_PREDICTION N_BODY_PERTURBATIONS SOLAR_RAD_PRESSURE EARTH_TIDES INTRACK_THRUST	required: spacecraft parameters

ANNEX H

RE-ENTRY INFORMATION DESCRIPTION

(INFORMATIVE)

H1 RE-ENTRY PREDICTION

H1.1 OVERVIEW

As of April 2017, slightly more than 24000, or 56 percent of all catalogued objects, have decayed and re-entered the atmosphere and several more re-enter every month. Re-entries can pose risk to ground based infrastructure and population, either due to the large mass of the spacecraft (e.g., Mir, Skylab, or the Salyut space stations), or due to hazardous materials (e.g., Cosmos 954). Although most re-entering objects are uncontrolled, controlled re-entry (e.g., Mir) can also provide additional information.

Predicting and simulating re-entries covers:

- long and medium term re-entry predictions (several years to a few weeks before re-entry);
- short term re-entry predictions (last days/weeks before re-entry; altitude below 200 km);
- break-up and survival (out of scope of the RDM); and
- ground impact and on-ground risk (partially out of scope of the RDM, due to limitations in break-up and survival estimations).

The following subsections describe re-entry simulations and modeling for the Earth, but similar considerations apply to other celestial bodies. More details can be found in chapter 9 of [I2], which describes re-entry simulations and how they applied to the Mir re-entry. Details on the European Space Agency's contributions to IADC (Inter-Agency Debris Coordination committee) re-entry campaigns can be found in referenced [I3] and [I4].

The estimation of the orbit lifetime is covered by an ISO standard, ISO 27852:2016 (reference [I5]). The standard focuses on long- and medium-term predictions and contains useful information to determine which mathematical models (e.g., gravity and atmospheric models) are appropriate in most situations. ISO is also working on a standard on atmospheric modelling, but as of the writing of this document, it has not been completed.

H1.2 NOMENCLATURE

The following terms will be used in equations in the following subsections:

a	=	semi-major axis
A	=	area
B	=	ballistic coefficient
C_d	=	drag coefficient
c_p	=	specific heat at constant pressure
g_0	=	sea-level gravitational acceleration
h_m	=	melting enthalpy
m	=	mass
Q	=	heat
t	=	time
T	=	temperature
T_m	=	melting temperature
v	=	velocity
V	=	volume
v_a	=	velocity relative to the atmosphere
v_{impact}	=	impact velocity
ε	=	radiation emission coefficient
ρ	=	density
σ	=	Stefan-Boltzmann constant

H1.3 LONG AND MEDIUM TERM RE-ENTRY PREDICTIONS

In the context of re-entry predictions, long and medium term means several years to a few weeks of orbital lifetime remaining. The current typical approach for these simulations is to use singly averaged perturbation equations integrated over a time step between 0.1 and 5 orbits. The perturbations accounted for by existing modeling software are: non-spherical Earth gravity, dynamic Earth atmosphere, luni-solar gravity perturbations, and solar radiation pressure combined with an oblate cylindrical Earth shadow. The end goal of these simulations is to estimate the remaining orbital lifetime.

Long and medium term re-entry predictions require simulating the decrease in the orbit's semi-major axis. For nearly circular orbits the rate of change of the semi-major axis with respect to time can be approximated by:

$$\frac{da}{dt} \approx -\frac{\rho a v_a}{B}$$

$$B = \frac{m}{C_d A}$$

where v_a is the velocity with respect to the atmosphere. While v_a and the atmospheric density can be estimated using Earth atmosphere models and orbit dynamics, the ballistic coefficient cannot. Uncontrolled objects tumble, so their angle of attack, and hence aerodynamic cross-section and drag coefficient are not constant. One approach to this issue is to retro-fit the simulated semi-major axis time history over observed values over a period of time by adjusting the ballistic coefficient.

Besides the ballistic coefficient, other sources of uncertainty in the results are: atmospheric density modeling (both the models themselves and unexpected space weather events), attitude, and the orbit state. A standard deviation of ± 20 percent for the remaining orbital lifetime is a good estimate for all the above in nominal conditions. More complex uncertainty modeling is also possible, e.g., accounting for orbit covariance and ballistic coefficient fit residuals.

H1.4 SHORT-TERM RE-ENTRY PREDICTIONS AND IMPACT

When the orbit altitude drops below ~ 200 km, the assumptions used in long term predictions (perturbation effects are small, no cross-coupling effects) no longer hold and more accurate modeling is needed. Numerical solutions to the perturbed equations of motion are used, typically accounting for: Earth gravity, luni-solar attraction, solar radiation pressure with umbra and penumbra transits, and atmospheric drag. Some success has been demonstrated for controlled re-entry with 6DOF numerical integration of the satellite states and attitude.

Below ~ 120 km atmospheric drag becomes the dominating force, and properly accounting for the change in drag coefficient between free-molecular flow, transitional, and continuum conditions is critical. For example, the drag coefficient of the Mir space station decreased from 2.21 in the free-molecular flow regime to 1.18 in the continuum subsonic regime. Atmospheric drag steepens the flight path, making the orbit more eccentric. At some point the re-entering object will achieve equilibrium free fall, leading to an impact velocity:

$$v_{\text{impact}} \approx \sqrt{\frac{2mg_0}{C_d A \rho_0}}$$

Dispersion in the impact location of a re-entry survivor object is driven by uncertainties in the area-to-mass ratio, aerodynamic coefficients (drag, lift, and side-force), air density, and initial orbit and attitude state and it is given in the along- and cross-track directions. Monte

Carlo simulations are needed to determine a geographic probability distribution. The probability density function in a given area can be computed as the fraction of impact in said area over total number of simulations. The probability distribution function (PDF) in the along-track direction is a distorted 2D Gaussian, further complicating matters.

Simpler approaches are sometimes used. Analytical formulae allow the computation of dispersion due to aerodynamic forces, based on lift, drag, and side-force coefficients and the ratio of lift and side-force, but they can be difficult to use and do not account for the main sources of uncertainty. An alternative is to assume a standard Gaussian distribution, compute the along-track dispersion by varying the aerodynamic drag term ($\rho \cdot B$) and use an empirical value for the cross-track dispersion (e.g., a 1-sigma value of 20 km).

H1.5 SURVIVAL AND BREAK-UP DURING RE-ENTRY

During re-entry aerodynamic braking and aerothermal heating can lead to:

- disintegration—the object breaks up into multiple fragments or losses external parts (e.g., solar panels, thermal shielding);
- mass loss—heating leads to melting and ablative mass loss; or
- total demise—the object burns up completely and there is no impact.

The heat flux due to aerothermal heating depends on the flow conditions (free molecular, transitional, continuum supersonic, and continuum subsonic), hence on object velocity and atmospheric density. How to estimate this flux is beyond the scope of this informative annex. The heat flux into the object leads to an increase in internal temperature, melting (once temperature is high enough), and radiating heat away from the object. Assuming a uniform composition leads to the following equations:

$$\dot{Q} = \rho c_p V \dot{T} + \epsilon \sigma A T^4, T < T_m$$

$$\dot{Q} = -\rho h_m \dot{V} + \epsilon \sigma A T^4, T = T_m$$

Until the object's surface reaches the melting temperature, the heat flux in is equal to the heat absorbed by increasing internal temperature and the heat radiated away. Once the surface reaches the melting temperature, the heat flux is equal to the heat lost by mass ablation and the heat radiated away. This leads to two ways in which an object can survive re-entry: absorb the re-entry heat without reaching the melting temperature or radiate the heat away efficiently. If the analysis is restricted to solid metallic spheres, very small objects (smaller than ~ 1 cm), can do the latter, while very large objects (larger than ~ 10 cm) can do the former. Objects in between (e.g., most nuts and bolts used in spacecraft assembly) will suffer total demise.

Simulating disintegration and mass loss for complex objects is a multi-disciplinary process, since spacecraft have complex shapes and contain a multitude of materials. The SCARAB tool, for example, can simulate it by dividing the spacecraft into basic elements, each with consistent material properties and each element into multiple voxels (volume elements). The simulation accounts for the forces acting on each element/voxel (as in H1.4) and computes heat fluxes, temperatures, and normal and shear stresses for a thermal and structural analysis. This determines break-ups (when stresses exceed the ultimate tensile or shear stress in the structure) and ablative mass loss.

Exchanging the information needed to accurately replicate these types of simulations is beyond the scope of the RDM. Furthermore, the tools needed to replicate the results are not widely available, which restricts usefulness. Break-ups during re-entry tend to happen at around 80 km altitude, when the combined aerodynamic and thermal loads are highest, but without knowing the structure of the object nothing more can be said.

H2 ATMOSPHERIC RE-ENTRY AND GROUND IMPACT DATA KEYWORDS

ORBIT_LIFETIME: The remaining time in orbit of the object, in days, from the EPOCH_TZERO keyword in the metadata. This is intended to be a coarse estimation, useful for long and medium term (more than a few days) re-entry prediction. The orbit lifetime is considered to end when the altitude permanently drops below the REENTRY_ALTITUDE. This keyword has two roles:

- Specify whether long/medium or short term re-entry simulations were used for the object (e.g., a high value means a long term simulation was performed); and
- Give an estimate of the remaining orbit lifetime, especially for long term predictions, with appropriate accuracy.

LIFETIME_DISPERSION: The uncertainty time window associated with the ORBIT_LIFETIME keyword and meant for long term re-entry predictions. A value of 20 percent provides an acceptable estimate for nominal conditions, accounting for uncertainties in the ballistic coefficient, atmospheric density, and orbit parameters.

Figure H-1 shows the type of information that can be generated from medium-term re-entry prediction RDMs. It assumes a new RDM containing an updated orbital lifetime prediction and uncertainty (fixed at 20 percent) is issued every couple of days. The predicted re-entry date (orbit lifetime + epoch t_zero) is plotted against the date at which the simulation was run (creation date), with the 20 percent dispersion plotted as well.

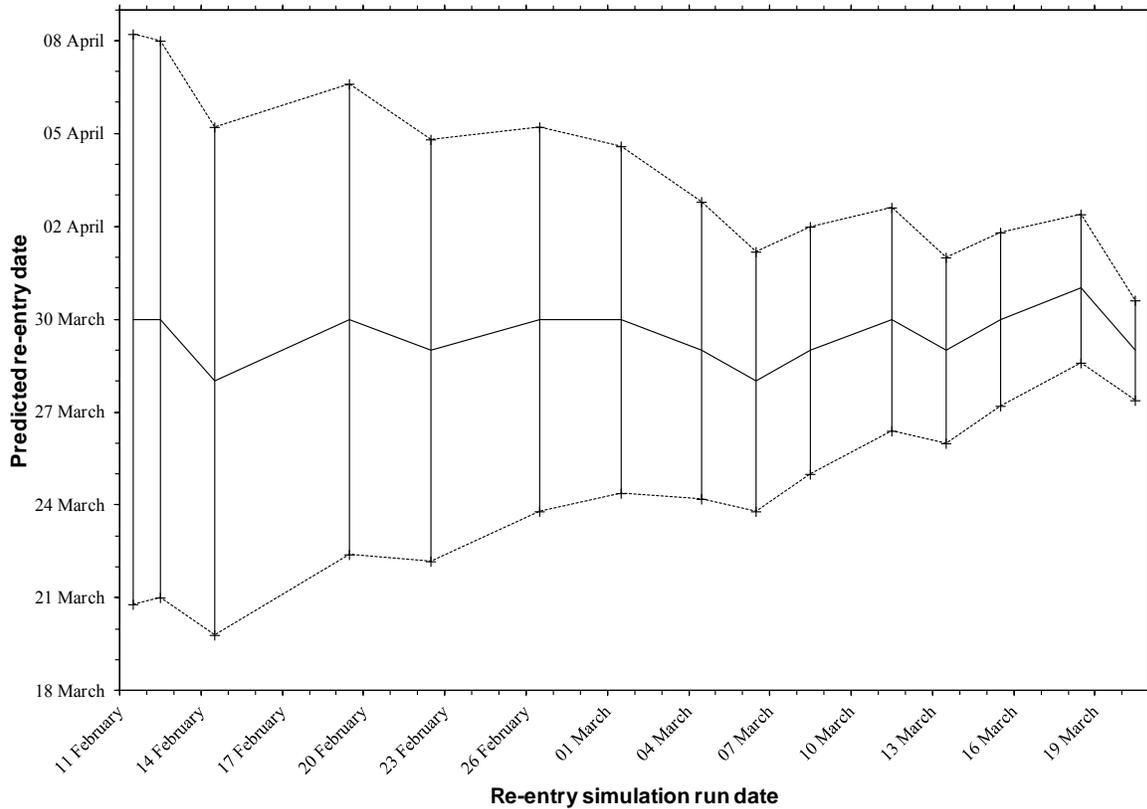


Figure H-1: Example of Medium Term Re-entry Prediction Data Use

REENTRY_ALTITUDE: The altitude at which the orbit lifetime ends and at which re-entry is defined. Depending on the particular re-entry event, different values can be specified, e.g., 150 km for ‘object captured by the Earth’s atmosphere’, 70 km for ‘object likely to break-up at this altitude’, or simply the altitude limit at which the re-entry simulation stops.

NOMINAL_REENTRY_EPOCH: Predicted re-entry epoch, providing much greater precision for short term (last couple of days before re-entry, when altitude is below 200 km) re-entry predictions.

REENTRY_WINDOW_START and **REENTRY_WINDOW_END:** Allow the RDM originator to specify a re-entry time window, which does not have to be symmetric around the nominal re-entry epoch. They can account for uncertainties in the modeling (atmospheric density, drag coefficient, attitude influence) or for under/over performance of thrusting maneuvers in a controlled re-entry.

PROBABILITY_OF_IMPACT: Probability of the object or **any** resulting fragments impacting the Earth (land or sea).

PROBABILITY_OF_BURN-UP: Total demise probability for the object and/or any resulting fragments.

PROBABILITY_OF_BREAK-UP: Probability of fragments being generated during re-entry, both ‘shedding’ of parts (e.g., solar panels, heat shields) and fragmentation of the main structure.

PROBABILITY_OF_LAND_IMPACT: Probability of the object or **any** resulting fragments impacting solid land. This is the first step in assessing any casualty probability, in conjunction with population density mapping.

NOMINAL_IMPACT_EPOCH: The nominal (predicted) epoch at which the object hits the surface of the Earth (either solid land or ocean).

IMPACT_WINDOW_START and **IMPACT_WINDOW_END:** The same as REENTRY_WINDOW_START and _END, but for the impact epoch.

IMPACT_REF_FRAME, NOMINAL_IMPACT_LON, _LAT, _ALT: Allow the specification of the nominal (predicted) impact location in geodetic coordinates.

IMPACT_n_CONFIDENCE, IMPACT_n_START_LON, IMPACT_n_START_LAT, IMPACT_n_STOP_LON, IMPACT_n_STOP_LAT, IMPACT_n_CROSS_TRCK: Uncertainties in the ground impact location are expressed in the along-track and cross-track directions, which means the (predicted) ground track needs to be known. Since the probability distribution is skewed, the method chosen to deal with these two issues is to:

- give the coordinates corresponding to the maximum probability, with the NOMINAL_IMPACT_LON and _LAT keywords;
- define up to three confidence intervals;
- give the coordinates of the two points on the ground track corresponding to the start and end of each of the (up to) three confidence intervals.

As long as at least three points are provided the ground track can be estimated as one or more segments of a great circle. The cross-track confidence intervals (in km) can be used to determine the swaths of impact probability, which can then be used together with population density mapping to determine the casualty probability.

The ground impact location and uncertainties are supposed to cover all eventual re-entry fragments (fragments generated during re-entry, not before). For example, if the re-entry data is obtained through Monte Carlo simulations, NOMINAL_IMPACT_LON, _LAT would correspond to the bin with the most impacts, the first swath would cover IMPACT_1_CONFIDENCE of the impacts, and so on. If analytical formulae are used for the 1-sigma confidence interval, IMPACT_1_CONFIDENCE should be 47 percent (for rectangular, rather than elliptical areas), the IMPACT_1_START/STOP_LAT/LON values can be determined from the formulae and the ground track, and IMPACT_1_CROSS_TRACK from the formula used.

H3 ORBIT DETERMINATION KEYWORDS

To promote consistency and ease implementation, the orbit determination keywords are the same as in the Conjunction Data Message (reference [I6]). These keywords are present to give the consumer of the message an idea of the quality of the data provided and when was the re-entering object last observed.

Observation: Unique measurement of a satellite's location from a single sensor at a single time (e.g., azimuth from a single sensor at a single time).

TIME_LASTOB_START and **TIME_LASTOB_END:** The start and end of a time interval that contains the time of the last accepted observation. For an exact time, the time interval is of zero duration (i.e., TIME_LASTOB_START = TIME_LASTOB_END).

RECOMMENDED_OD_SPAN: How many days of observations were recommended for the OD of the object.

ACTUAL_OD_SPAN: The actual time span used for the OD of the object based on the observations available and the RECOMMENDED_OD_SPAN.

OBS_AVAILABLE: The number of observations, for the recommended time span, that were available for the OD.

OBS_USED: The number of observations, for the recommended time span, that were accepted for the OD.

Sensor Track: A set of at least three observations for the same object, observed by the same sensor, where each observation is within a specified number of minutes (which is dependent on the orbit regime of the object) of the other observations in the track.

TRACKS_AVAILABLE: The number of sensor tracks, for the recommended time span, that were available for the OD. This provides information about the independence of the observational data used in the OD.

TRACKS_USED: The number of sensor tracks, for the recommended time span, that were accepted for the OD. This provides information about the independence of the observational data used in the OD.

WEIGHTED_RMS:

$$\text{Weighted RMS} = \sqrt{\frac{\sum_{i=1}^N w_i (y_i - y_{i,estimated})^2}{N}}$$

Where:

y_i is the i th observation;

$y_{i,estimated}$ is the estimated value (from the resulting orbit) of y_i ;

w_i is the weighting of the observation; and

N is the total number of observations.

This is a value that can generally identify the quality of the most recent orbit update, and is used by the analyst in evaluating the OD process.

ANNEX I**INFORMATIVE REFERENCES****(INFORMATIVE)**

- [11] *Navigation Data—Definitions and Conventions*. Issue 3. Report Concerning Space Data System Standards (Green Book), CCSDS 500.0-G-3. Washington, D.C.: CCSDS, May 2010.
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- [14] Benjamin Bastida Virgili, et al. “Practicalities of Re-entry Predictions—The VEGA-01 AVUM Case.” In *Proceedings of the 7th European Conference on Space Debris (18–21 April 2017, Darmstadt, Germany)*. Edited by T. Flohrer and F. Schmitz. Darmstadt, Germany: ESA Space Debris Office, 2017.
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